Short-circuits in ES

Short-circuit:

- cross fault, quick emergency change in ES
- the most often fault in ES
- transient events occur during short-circuits

Short-circuit formation:

• fault connection between phases or between phase(s) and the ground in the system with the grounded neutral point

Main causes:

- insulation defect caused by overvoltage
- direct lightning strike
- insulation aging
- direct damage of overhead lines or cables

Short-circuit impacts:

- total impedance of the network affected part decreases
- currents are increasing => so called short-circuit currents I_k
- the voltage decreases near the short-circuit
- Ik impacts causes device heating and power strain
- problems with I_k disconnecting, electrical arc and overvoltage occurred during the short-circuit
- synchronism disruption of ES working in parallel
- communication line disturbing => induced voltages

Note: In short-circuit places transient resistances arise.

- transient resistance is a sum of electrical arc resistance and resistance of other I_k way parts (determination of exact resistances is difficult)
- current and electrical arc length is changing during short-circuit => resistance of electrical arc is also changing

• transient resistances are neglected for I_k calculation (dimensioning of electrical devices) $\rightarrow \underline{perfect \ short-circuits}$

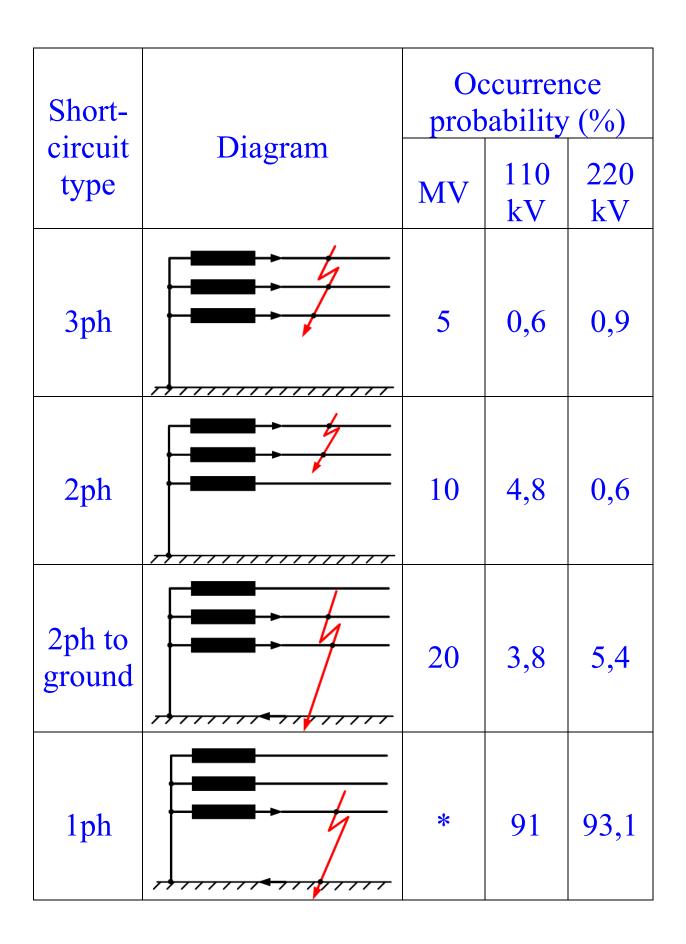
Short-circuits types

Symmetrical short-circuits:

- Three-phase short-circuit => all 3 phases are affected by short-circuit
 - Ittle occurrence in the case of overhead lines
 - the most occurrences in the case of cable lines => other kinds of faults change to 3ph short-circuit due to electrical-arc impact

Unbalanced (asymmetrical) short-circuits:

- phase-to-phase short-circuit
- double-phase-to-ground short-circuit
- single-phase-to-ground short-circuit:
 - In MV a different kind of fault => so called ground fault
 - in case of ground fault in MV (insulated or indirectly grounded neutral point) => no change in LV (grounded neutral point)



Short-circuit current time behaviour

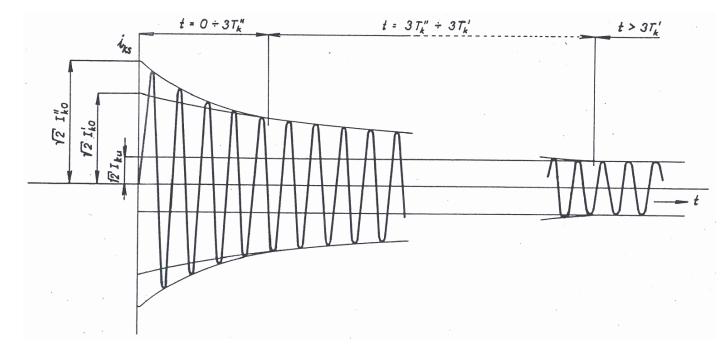
$$W_{L} = \frac{1}{2}Li^{2}$$
$$P = \frac{dW_{L}}{dt} < \infty \rightarrow \text{transient event}$$

Time behaviour: open-circuit, resistances neglected \rightarrow reactance, current of inductive character, higher I_k values

Impact of R on I_k attributes:

- finite R values decrease short-circuit impacts
- R neglecting results in time constants prolongation $\tau = L/R$

$U = U_{max}$ in the short-circuit moment $\rightarrow I_k$ starts from zero (min. value)

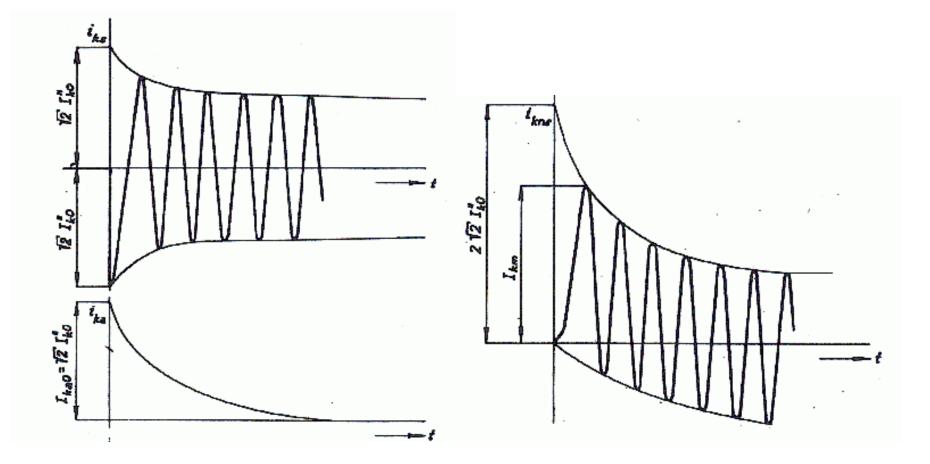


Short-circuit components (f = 50 Hz):

- sub-transient exponential envelope, T''_k (damping winding)
- transient exponential envelope, T'_k (field winding)
- steady-state constant magnitude

It is caused by synchronous machine behaviour during short-circuit \rightarrow more significant during short-circuits near the machine.

U = 0 in the short-circuit moment $\rightarrow I_k$ starts from max. value



Values

- symmetrical short-circuit current I_{ks} steady-state, transient and sub-transient component sum, RMS value
- sub-transient short-circuit current $I''_k I_{ks}$ RMS value in the period of sub-transient component $t \doteq (0 \div 3T''_k)$
- initial sub-transient short-circuit current $I''_{k0} I''_{k}$ value in the moment of short-circuit origin t = 0
- DC component I_{ka} disappears exponentially, T_{ka}
- peak short-circuit current I_{km} the first half-period magnitude during the maximal DC component

Short-circuits in 3ph system

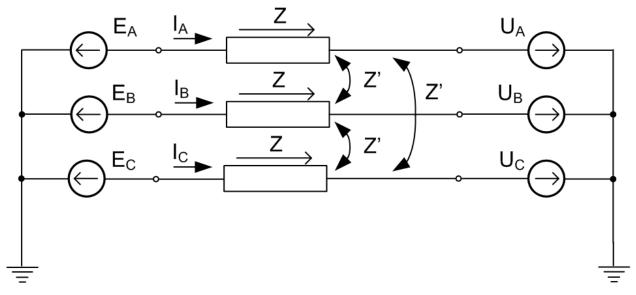
Conversion between phase values and symmetrical components

$$(\mathbf{U}_{ABC}) = \begin{pmatrix} \hat{\mathbf{U}}_{A} \\ \hat{\mathbf{U}}_{B} \\ \hat{\mathbf{U}}_{C} \end{pmatrix} = \begin{pmatrix} 1 & 1 & 1 \\ \hat{a}^{2} & \hat{a} & 1 \\ \hat{a} & \hat{a}^{2} & 1 \end{pmatrix} \begin{pmatrix} \hat{\mathbf{U}}_{1} \\ \hat{\mathbf{U}}_{2} \\ \hat{\mathbf{U}}_{0} \end{pmatrix} = (\mathbf{T})(\mathbf{U}_{120})$$
$$(\mathbf{U}_{120}) = \begin{pmatrix} \hat{\mathbf{U}}_{1} \\ \hat{\mathbf{U}}_{2} \\ \hat{\mathbf{U}}_{0} \end{pmatrix} = \frac{1}{3} \begin{pmatrix} 1 & \hat{a} & \hat{a}^{2} \\ 1 & \hat{a}^{2} & \hat{a} \\ 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} \hat{\mathbf{U}}_{A} \\ \hat{\mathbf{U}}_{B} \\ \hat{\mathbf{U}}_{C} \end{pmatrix} = (\mathbf{T}^{-1})(\mathbf{U}_{ABC})$$

Impedance matrix in symmetrical components (for series sym. segment)

$$(Z_{120}) = \begin{pmatrix} \hat{Z}_1 & 0 & 0 \\ 0 & \hat{Z}_2 & 0 \\ 0 & 0 & \hat{Z}_0 \end{pmatrix} = \begin{pmatrix} \hat{Z} - \hat{Z}' & 0 & 0 \\ 0 & \hat{Z} - \hat{Z}' & 0 \\ 0 & 0 & \hat{Z} + 2\hat{Z}' \end{pmatrix}$$

3ph system during short-circuit – internal generator voltage E (or U_i)



$$(E_{ABC}) = (Z_{ABC})(I_{ABC}) + (U_{ABC})$$

Symmetrical system (independent systems 1, 2, 0)

$$(E_{120}) = (Z_{120})(I_{120}) + (U_{120})$$

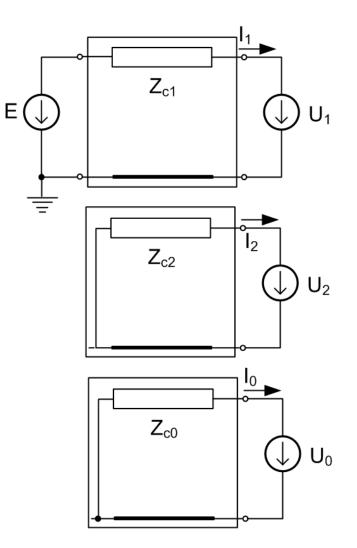
$$\hat{E}_1 = \hat{Z}_1 \hat{I}_1 + \hat{U}_1 \\
\hat{E}_2 = \hat{Z}_2 \hat{I}_2 + \hat{U}_2 \\
\hat{E}_0 = \hat{Z}_0 \hat{I}_0 + \hat{U}_0$$

Generator symmetrical voltage \rightarrow only positive sequence component Reference phase A:

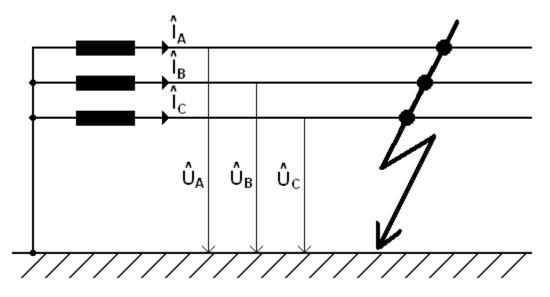
$$(\mathbf{E}_{120}) = (\mathbf{T}^{-1})(\mathbf{E}_{ABC}) = \frac{1}{3} \begin{pmatrix} 1 & \hat{a} & \hat{a}^2 \\ 1 & \hat{a}^2 & \hat{a} \\ 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} \hat{\mathbf{E}}_A \\ \hat{a}^2 \hat{\mathbf{E}}_A \\ \hat{a} \hat{\mathbf{E}}_A \end{pmatrix} = \begin{pmatrix} \hat{\mathbf{E}}_A \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} \hat{\mathbf{E}}_A \\ 0 \end{pmatrix} = \begin{pmatrix} \hat{\mathbf{E}$$

Negative and zero sequence are caused by voltage unbalance in the faulted place.

In the fault point 6 quantities $(U_{120}, I_{120}) \rightarrow 3$ equations necessary to be added by other 3 equations according to the short-circuit type (local unbalance description).



Three-phase (to-ground) short-circuit



3 char. equations

$$\hat{U}_{A} = \hat{U}_{B} = \hat{U}_{C} = 0$$

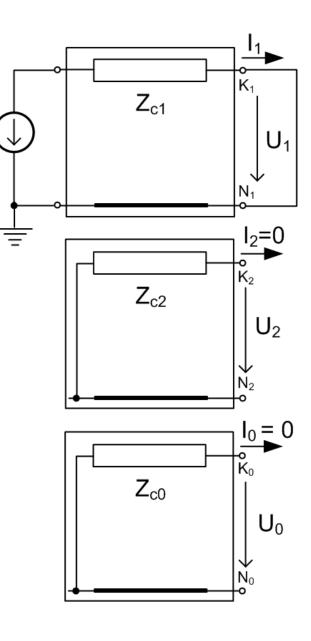
Components

$$(\mathbf{U}_{120}) = (\mathbf{T}^{-1})(\mathbf{U}_{ABC}) = \frac{1}{3} \begin{pmatrix} 1 & \hat{a} & \hat{a}^2 \\ 1 & \hat{a}^2 & \hat{a} \\ 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$
$$\hat{\mathbf{U}}_1 = \hat{\mathbf{U}}_2 = \hat{\mathbf{U}}_0 = \mathbf{0}$$
$$\hat{\mathbf{I}}_1 = \frac{\hat{\mathbf{E}}}{\hat{\mathbf{Z}}_1}; \ \hat{\mathbf{I}}_2 = \mathbf{0}; \ \hat{\mathbf{I}}_0 = \mathbf{0}$$

Phases

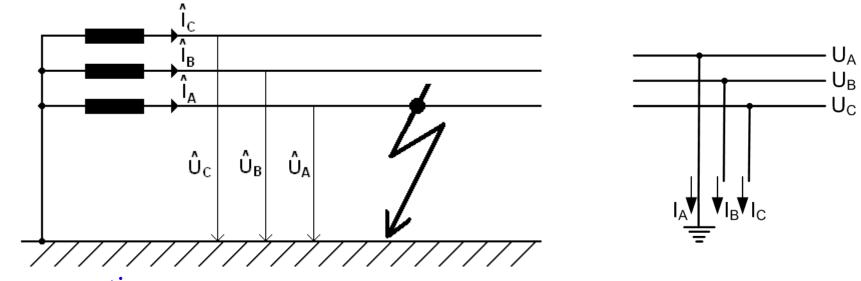
$$(I_{ABC}) = (T)(I_{120})$$
$$\hat{I}_{A} = \frac{\hat{E}}{\hat{Z}_{1}}; \ \hat{I}_{B} = \hat{a}^{2} \frac{\hat{E}}{\hat{Z}_{1}}; \ \hat{I}_{C} = \hat{a} \frac{\hat{E}}{\hat{Z}_{1}}$$

Only the positive-sequence component included.



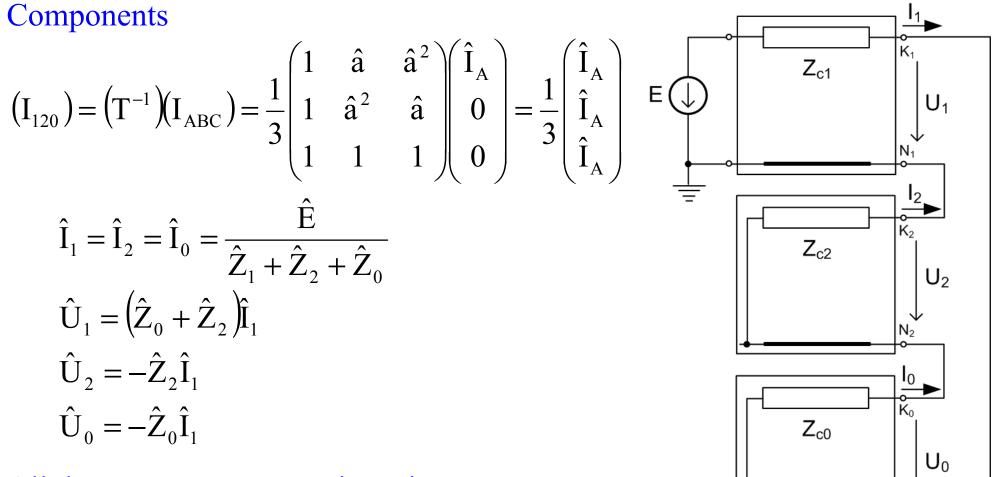
Е

Single-phase-to-ground short-circuit



3 char. equations

$$\hat{U}_{A} = 0; \ \hat{I}_{B} = \hat{I}_{C} = 0$$



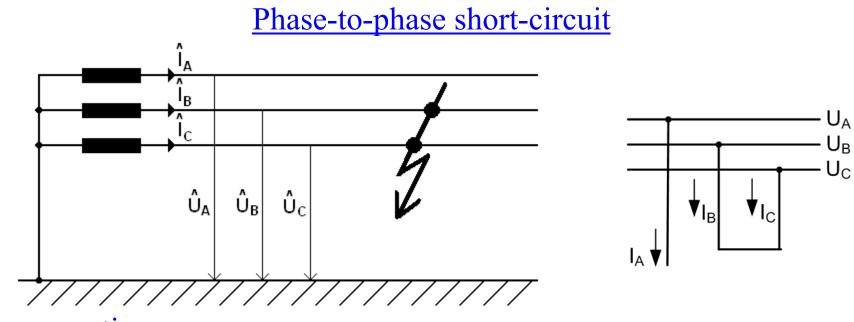
All three components are in series.

Phases

$$(I_{ABC}) = (T)(I_{120}) = \begin{pmatrix} 1 & 1 & 1 \\ \hat{a}^2 & \hat{a} & 1 \\ \hat{a} & \hat{a}^2 & 1 \end{pmatrix} \begin{pmatrix} \hat{I}_1 \\ \hat{I}_1 \\ \hat{I}_1 \end{pmatrix} = \begin{pmatrix} 3\hat{I}_1 \\ 0 \\ 0 \end{pmatrix}$$

$$\hat{I}_A = \frac{3\hat{E}}{\hat{Z}_1 + \hat{Z}_2 + \hat{Z}_0}; \quad \hat{I}_B = 0; \quad \hat{I}_C = 0$$

$$(U_{ABC}) = (T)(U_{120}) = \begin{pmatrix} 1 & 1 & 1 \\ \hat{a}^2 & \hat{a} & 1 \\ \hat{a} & \hat{a}^2 & 1 \end{pmatrix} \begin{pmatrix} (\hat{Z}_0 + \hat{Z}_2)\hat{I}_1 \\ -\hat{Z}_2\hat{I}_1 \\ -\hat{Z}_0\hat{I}_1 \end{pmatrix} = \begin{pmatrix} 0 \\ (\hat{a}^2 - \hat{a})\hat{Z}_2 + (\hat{a}^2 - 1)\hat{Z}_0 \\ (\hat{a} - \hat{a}^2)\hat{Z}_2 + (\hat{a} - 1)\hat{Z}_0 \end{pmatrix} \hat{I}_1$$



3 char. equations

$$\hat{U}_{B} = \hat{U}_{C}; \hat{I}_{B} = -\hat{I}_{C}; \hat{I}_{A} = 0$$

Components

 K_0

 U_0

 Z_{c0}

Positive and negative components in parallel.

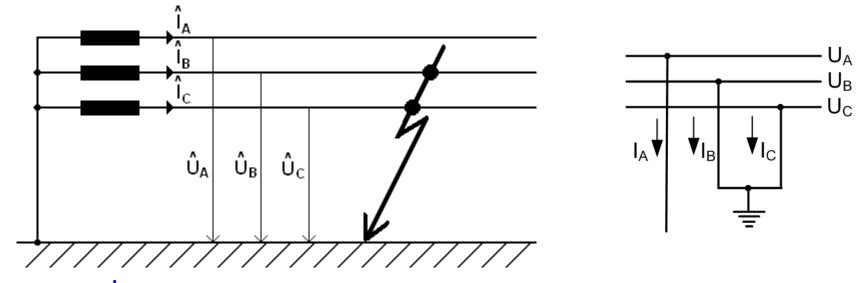
Phases

$$(I_{ABC}) = (T)(I_{120}) = \begin{pmatrix} 1 & 1 & 1 \\ \hat{a}^2 & \hat{a} & 1 \\ \hat{a} & \hat{a}^2 & 1 \end{pmatrix} \begin{pmatrix} \hat{I}_1 \\ -\hat{I}_1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ -j\sqrt{3}\hat{I}_1 \\ j\sqrt{3}\hat{I}_1 \end{pmatrix}$$

$$\hat{I}_A = 0; \ \hat{I}_B = \frac{-j\sqrt{3}\hat{E}}{\hat{Z}_1 + \hat{Z}_2}; \ \hat{I}_C = \frac{j\sqrt{3}\hat{E}}{\hat{Z}_1 + \hat{Z}_2}$$

$$(U_{ABC}) = (T)(U_{120}) = \begin{pmatrix} 1 & 1 & 1 \\ \hat{a}^2 & \hat{a} & 1 \\ \hat{a} & \hat{a}^2 & 1 \end{pmatrix} \begin{pmatrix} \hat{U}_1 \\ \hat{U}_1 \\ 0 \end{pmatrix} = \begin{pmatrix} 2\hat{U}_1 \\ -\hat{U}_1 \\ -\hat{U}_1 \end{pmatrix} = \begin{pmatrix} 2\hat{Z}_2 \cdot \hat{I}_1 \\ -\hat{Z}_2 \cdot \hat{I}_1 \\ -\hat{Z}_2 \cdot \hat{I}_1 \end{pmatrix}$$

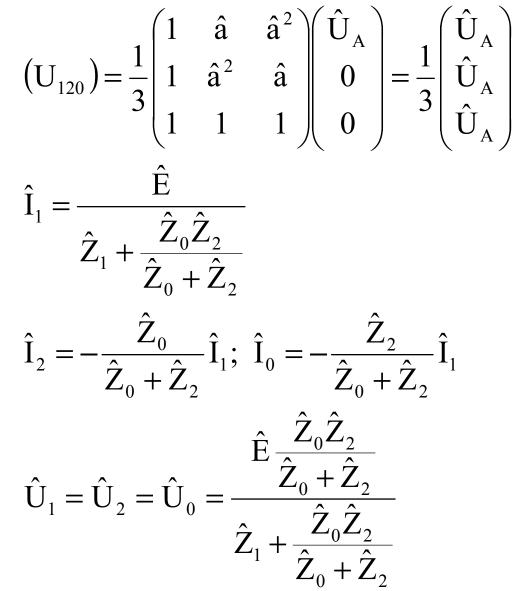
Double-phase-to-ground short-circuit

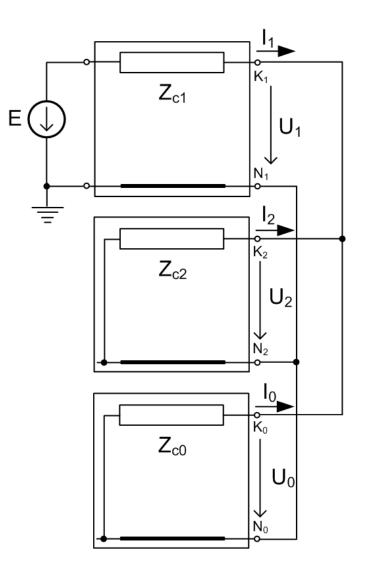


3 char. equations

$$\hat{U}_{B} = \hat{U}_{C} = 0; \ \hat{I}_{A} = 0$$

Components





All three components are in parallel.

Phases $(I_{ABC}) = (T)(I_{120})$ $\hat{I}_{B} = \frac{\hat{E}(\hat{Z}_{0}(\hat{a}^{2} - \hat{a}) + \hat{Z}_{2}(\hat{a}^{2} - 1))}{\hat{Z}_{1}\hat{Z}_{2} + \hat{Z}_{0}\hat{Z}_{1} + \hat{Z}_{0}\hat{Z}_{2}}$ $\hat{I}_{C} = \frac{\hat{E}(\hat{Z}_{0}(\hat{a} - \hat{a}^{2}) + \hat{Z}_{2}(\hat{a} - 1))}{\hat{Z}_{0}\hat{Z}_{0} + \hat{Z}_{0}\hat{Z}_{0} + \hat{Z}_{0}\hat{Z}_{0} + \hat{Z}_{0}\hat{Z}_{0}}$ $(U_{ABC}) = (T)(U_{120}) = \begin{pmatrix} 1 & 1 & 1 \\ \hat{a}^2 & \hat{a} & 1 \\ \hat{a} & \hat{a}^2 & 1 \end{pmatrix} \begin{pmatrix} \hat{U}_1 \\ \hat{U}_1 \\ \hat{U}_1 \\ \hat{U}_1 \end{pmatrix} = \begin{pmatrix} 3\hat{U}_1 \\ 0 \\ 0 \end{pmatrix}$

Components during short-circuit:

3ph	positive
2ph	positive, negative
2ph ground	positive, negative, zero
1ph	positive, negative, zero

Short-circuits calculation by means of relative values

Relative values – related to a defined base.

 $\begin{array}{ll} \text{base power (3ph)} & S_v \left(\text{VA} \right) \\ \text{base voltage (phase-to-phase)} & U_v \left(\text{V} \right) \\ \text{base current} & I_v \left(\text{A} \right) \\ \text{base impedance} & Z_v \left(\Omega \right) \end{array}$

$$S_{v} = \sqrt{3}U_{v}I_{v}$$
$$Z_{v} = \frac{U_{vf}}{I_{v}}$$

Relative impedance

$$z = \frac{Z}{Z_{v}} = \frac{Z}{\frac{U_{vf}}{I_{v}}} = Z \frac{I_{v}}{U_{vf}} \frac{3U_{vf}}{3U_{vf}} = Z \frac{S_{v}}{3U_{vf}^{2}} = Z \frac{S_{v}}{U_{v}^{2}}$$

Initial sub-transient short-circuit current (3ph short-circuit)

$$I_{k0}'' = \left| \hat{I}_{A} \right| = \frac{\left| \hat{U}_{f} \right|}{\left| \hat{Z}_{1} \right|}$$
$$Z_{1} = Z_{1} \frac{U_{v}^{2}}{S_{v}}$$
$$I_{k0}'' = \frac{\frac{U_{v}}{\sqrt{3}}}{Z_{1} \frac{U_{v}^{2}}{S_{v}}} = \frac{1}{Z_{1}} \frac{S_{v}}{\sqrt{3}U_{v}} = \frac{1}{Z_{1}} I_{v}$$

Initial sub-transient short-circuit power

$$S_{k0}'' = \sqrt{3}U_{v}I_{k0}'' = \sqrt{3}U_{v}\frac{I_{v}}{z_{1}} = \frac{1}{z_{1}}S_{v}$$

Similarly for 1ph short-circuit

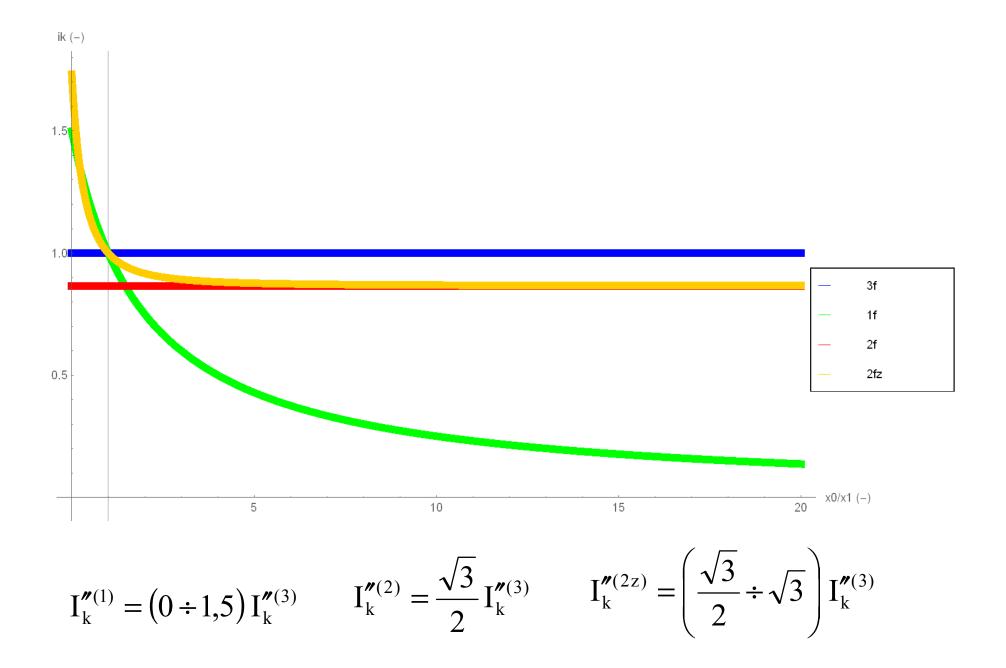
$$I_{k0}^{"(1)} = \frac{3}{z_1 + z_2 + z_0} I_v$$

2ph short-circuit

$$I_{k0}^{"(2)} = \frac{\sqrt{3}}{z_1 + z_2} I_v$$

Note: Sometimes it is respected generator loading, more precisely higher internal generator voltage than nominal one.

$$I_{k0}'' = k \frac{1}{z_1} I_v$$
$$k \ge 1$$



Short-circuit currents impacts

Mechanical impacts

Influence mainly at tightly placed stiff conductors, supporting insulators, disconnectors, construction elements,...

Forces frequency 2f at AC \rightarrow dynamic strain.

Force on the conductor in magnetic field $F = B \cdot I \cdot l \cdot \sin \alpha \quad (N)$ $B = \mu \cdot H \quad (T)$ $\mu_0 = 4\pi \cdot 10^{-7} \quad (H/m)$ $\alpha - \text{angle between mag. induction vector and the conductor axis (current direction)}$

Magnetic field intensity in the distance **a** from the conductor

$$H = \frac{I}{2\pi a} \quad (A/m)$$

2 parallel conductors \rightarrow force perpendicular to the conductor axis $(\sin \alpha = 1) \rightarrow$ it is the biggest

$$F = 4\pi \cdot 10^{-7} \frac{I}{2\pi a} I \cdot 1 = 2 \cdot 10^{-7} \frac{I^2}{a} 1 \quad (N)$$

The highest force corresponds to the highest immediate current value \rightarrow peak short-circuit current I_{km} (1st magnitude after s.-c. origin)

$$I_{km} = \sqrt{2} I_{k0}'' \left(1 + e^{-0.01/T_k} \right) = \kappa \sqrt{2} I_{k0}'' \quad (A)$$

 κ – peak coefficient according to grid type ($\kappa_{LV} = 1,8$; $\kappa_{HV} = 1,7$) theoretical range $\kappa = 1 \div 2$

T_k – time constant of equivalent short-circuit loop (L_e/R_e) i.e. for DC component of short-circuit current

 I''_{k0} - initial sub-transient short-circuit current

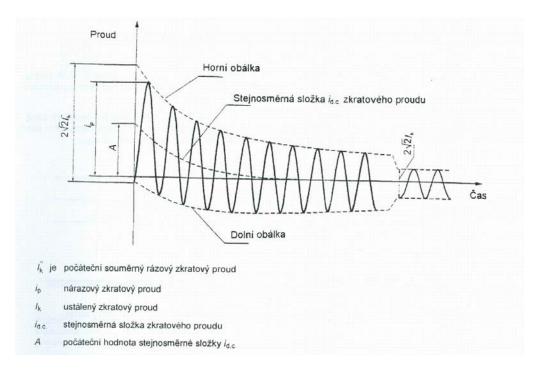
Real value differs according to the short-circuit origin moment. AC component decreasing slower than for DC therefore neglected. Max. instantaneous force on the conductor length unit

$$f = 2 \cdot k_1 \cdot k_2 \cdot 10^{-7} \frac{I_{km}^2}{a} (N/m)$$

 k_1 – conductor shape coefficient

k₂ – conductors configuration and currents phase shift coefficient

a – conductors distance



Heat impacts

Key for dimensioning mainly at freely placed conductors. They are given by heat accumulation influenced by time-changing current during short-circuit time t_k (adiabatic phenomenon).

Heat produced in conductors

$$Q = \int_{0}^{t_{k}} R(\vartheta) \cdot i_{k}^{2}(t) dt \quad (J)$$

<u>Thermal equivalent current</u> – current RMS value which has the same heating effect in the short-circuit duration time as the real short-circuit current

$$I_{ke}^{2}t_{k} = \int_{0}^{t_{k}} i_{k}^{2}(t)dt \qquad I_{ke} = \sqrt{\frac{1}{t_{k}}}\int_{0}^{t_{k}} i_{k}^{2}(t)dt \quad (A)$$

Calculation according to k_e coefficient as I''_k multiple $I_{ke} = k_e I''_k$

Ground fault in three-phase systems

MV grids without a directly grounded neutral point (distribution systems) \rightarrow single-phase ground fault has a different character than short-circuits (small capacitive current).

Fault current proportional to the system extent.

 $I_p > 5 A \rightarrow \text{arc formation} \rightarrow \text{conductors, towers, insulators burning} \rightarrow 2\text{ph}$, 3ph short-circuits (mainly at cables)

GF compensation \rightarrow uninterrupted system operation (until the failure clearance, short supply break), arc self-extinguishing

Ground fault

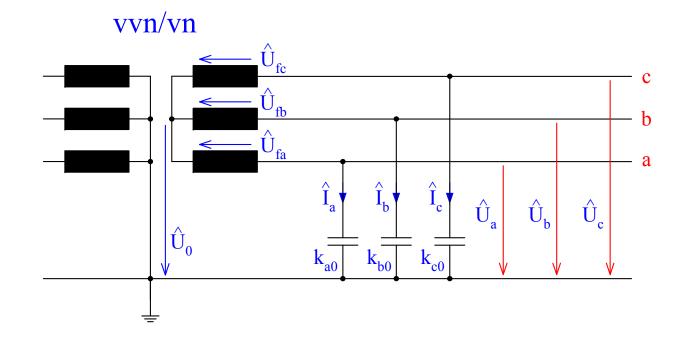
• resistive (100x Ω), metal and arc (x Ω)

Conditions in a system with insulated neutral point

Assumptions: considered only capacities to the ground, symmetrical source voltage, open-circuit system

Insulated neutral point – systems of a small extent, $I_p < 10 \text{ A}$

Before the fault



$$\hat{U}_{a,b,c} - \hat{U}_0 - \hat{U}_{fa,b,c} = 0$$

$$\hat{I}_{a,b,c} = j\omega k_{a,b,c0} \hat{U}_{a,b,c}$$

System with insulated neutral point $\hat{I}_a + \hat{I}_b + \hat{I}_c = 0$

Symmetrical source

$$\hat{U}_{fb} = \hat{a}^2 \hat{U}_{fa}, \ \hat{U}_{fc} = \hat{a} \hat{U}_{fa}$$

Neutral point voltage

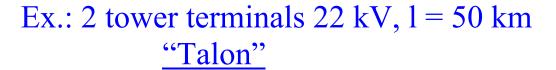
$$\hat{\mathbf{U}}_{0} = -\frac{\mathbf{k}_{a0} + \hat{a}^{2}\mathbf{k}_{b0} + \hat{a}\mathbf{k}_{c0}}{\mathbf{k}_{a0} + \mathbf{k}_{b0} + \mathbf{k}_{c0}}\hat{\mathbf{U}}_{fa}$$

Unbalanced capacities

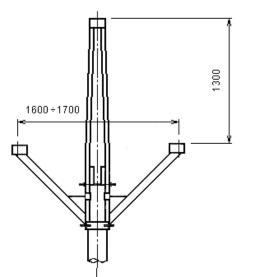
$$\hat{U}_0 \neq 0$$

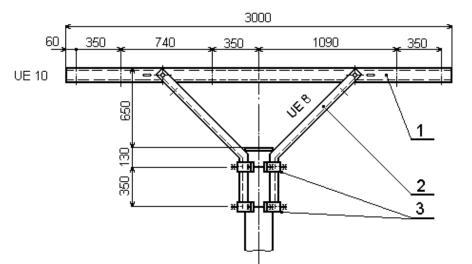
Symmetrical capacities

$$\mathbf{k}_{a0} = \mathbf{k}_{b0} = \mathbf{k}_{c0} = \mathbf{k}_{0} \implies \hat{\mathbf{U}}_{0} = \mathbf{0}$$





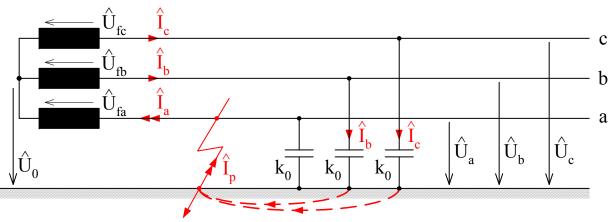




$$\begin{array}{ll} k_{a0} = k_{c0} = 4,16 \ nF/km & k_{a0} = k_{c0} = 4,48 \ nF/km \\ k_{b0} = 4,00 \ nF/km & (\Delta = 3,8 \%) & k_{b0} = 3,90 \ nF/km & (\Delta = 12,9 \%) \\ U_0 = 165 \ V & (1,3 \%) & U_0 = 573 \ V & (4,5 \%) \\ U_a = U_c = 12620 \ V & U_a = U_c = 12425 \ V \\ U_b = 12867 \ V & U_b = 13275 \ V \\ U_{fn} = 12702 \ V \end{array}$$

Perfect (metal) durable ground fault

Symmetrical system



Fault current composed of 2 capacitive currents in the disaffected phases.

$$\begin{split} \hat{\mathbf{U}}_{a} &= \mathbf{0} \\ \hat{\mathbf{I}}_{p} &= \hat{\mathbf{I}}_{a} = \hat{\mathbf{I}}_{b} + \hat{\mathbf{I}}_{c} \\ \hat{\mathbf{I}}_{b} &= \mathbf{j}\omega\mathbf{k}_{0}\hat{\mathbf{U}}_{b} \qquad \hat{\mathbf{I}}_{c} = \mathbf{j}\omega\mathbf{k}_{0}\hat{\mathbf{U}}_{c} \\ \hat{\mathbf{U}}_{a} - \hat{\mathbf{U}}_{0} - \hat{\mathbf{U}}_{fa} = \mathbf{0} \implies \hat{\mathbf{U}}_{0} = -\hat{\mathbf{U}}_{fa} \end{split}$$

$$\hat{U}_{b} - \hat{U}_{0} - \hat{U}_{fb} = 0 \implies \hat{U}_{b} = \hat{U}_{0} + \hat{U}_{fb} = (-1 + \hat{a}^{2})\hat{U}_{fa} = -\sqrt{3}e^{j30^{\circ}}\hat{U}_{fa} !$$
$$\hat{U}_{c} - \hat{U}_{0} - \hat{U}_{fc} = 0 \implies \hat{U}_{c} = \hat{U}_{0} + \hat{U}_{fc} = (-1 + \hat{a})\hat{U}_{fa} = -\sqrt{3}e^{-j30^{\circ}}\hat{U}_{fa} !$$

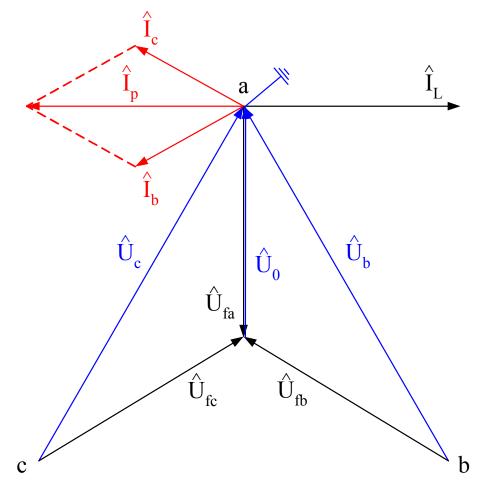
→ affected phase voltage – zero neutral point voltage – phase-to-ground value disaffected phases voltage – phase-to-phase value

Ground fault current

$$\hat{I}_{p} = \hat{I}_{b} + \hat{I}_{c} = j\omega k_{0} (\hat{U}_{b} + \hat{U}_{c})$$

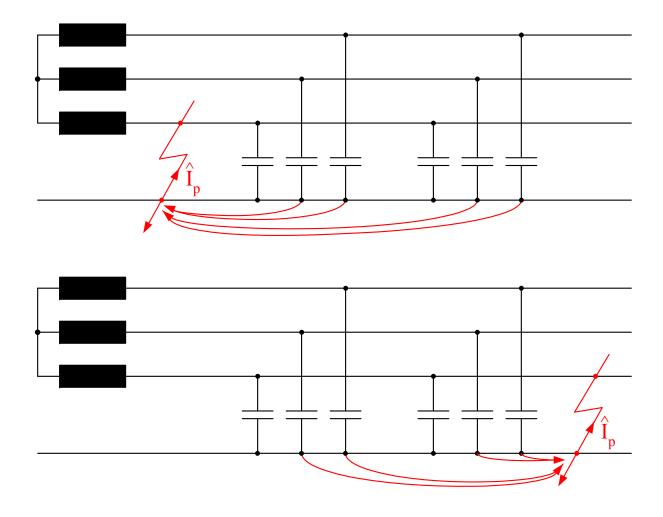
= $j\omega k_{0} [(-1 + \hat{a}^{2}) + (-1 + \hat{a})]\hat{U}_{fa}$
= $j\omega k_{0} (-2 + \hat{a}^{2} + \hat{a} + 1 - 1)\hat{U}_{fa}$
 $\hat{I}_{p} = -3j\omega k_{0}\hat{U}_{fa} = 3j\omega k_{0}\hat{U}_{0}$ (A;s⁻¹, F, V)

Voltage and current conditions



Fault current depends on the total system extent and almost doesn't depend on the fault point distance from the transformer.

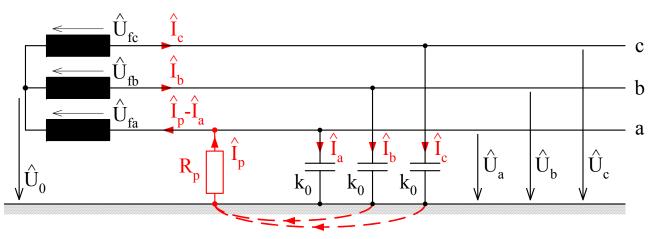
$$I_{p} = 3\omega k_{01} lU_{f} \quad (A; s^{-1}, F/km, km, V)$$



Note: overhead 22 kV – current c. 0,06 A/km cables 22 kV – current c. 4 A/km
Note: MV system can be operated also with GF, on LV level again 3-phase supplying due to transformers MV/LV D/yn (Y/zn)

TalonHorizontal $I_{pa} = I_{pc} = 2,44 \text{ A}$ $I_{pa} = I_{pc} = 2,51 \text{ A}$ $I_{pb} = 2,49 \text{ A}$ $I_{pb} = 2,68 \text{ A}$

Resistive ground fault



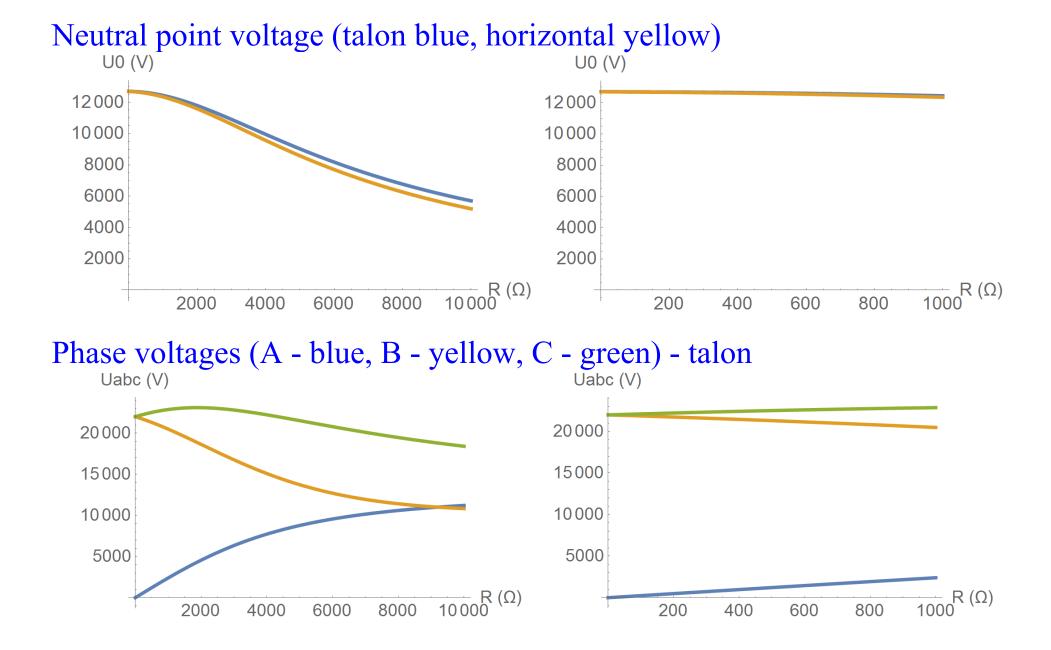
Affected phase voltage non-zero

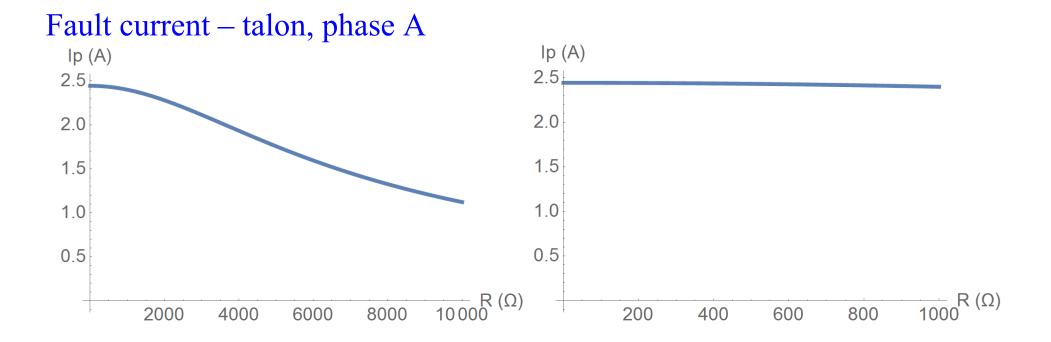
$$\hat{I}_{p} = -\hat{U}_{a} / R_{p} = \hat{I}_{a} + \hat{I}_{b} + \hat{I}_{c}$$

Neutral point voltage

$$\hat{U}_{0} = -\frac{j\omega(k_{a0} + \hat{a}^{2}k_{b0} + \hat{a}k_{c0}) + R_{p}^{-1}}{j\omega(k_{a0} + k_{b0} + k_{c0}) + R_{p}^{-1}}\hat{U}_{fa}$$

 $R_{p} = 0 \qquad \hat{U}_{0} = -\hat{U}_{fa}$ $R_{p} = \infty \qquad \hat{U}_{0} = 0 \text{ (for symmetrical capacities)}$

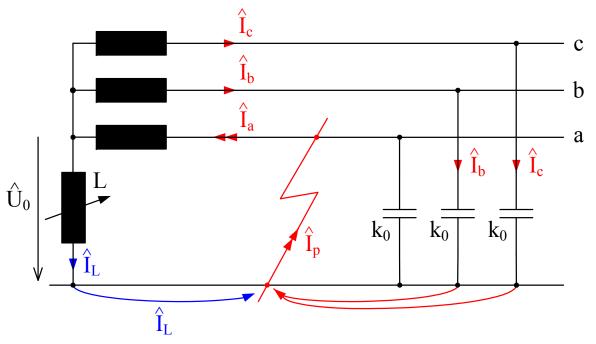




Ground fault current compensation

Compensation in systems where $I_p > 5A$ - suitable $I_p > 10A$ - necessary

Method: continuously controlled arc-suppression coil (Petersen coil) between the transformer neutral point and the ground (in case of transformers with D winding by means of grounding transformer with Zn, Yn – artificial neutral point)



Faultless state

 $U_0 = 0$ - symmetrical capacities $U_0 \approx x \cdot 0,01 U_f$ - usual unbalance

Perfect ground fault

$$\hat{\mathbf{U}}_{0} = -\hat{\mathbf{U}}_{\mathrm{fa}}$$

Arc-suppression coil current

$$\hat{\mathbf{I}}_{\mathrm{L}} = -j \frac{\hat{\mathbf{U}}_{0}}{\omega \mathrm{L}}$$

Total compensation

$$\hat{I}_{L} = -\hat{I}_{p}$$
$$-j\frac{\hat{U}_{0}}{\omega L} = -3j\omega k_{0}\hat{U}_{0}$$

Hence

$$L = \frac{1}{3\omega^2 k_0}$$
 (H; s⁻¹, F)

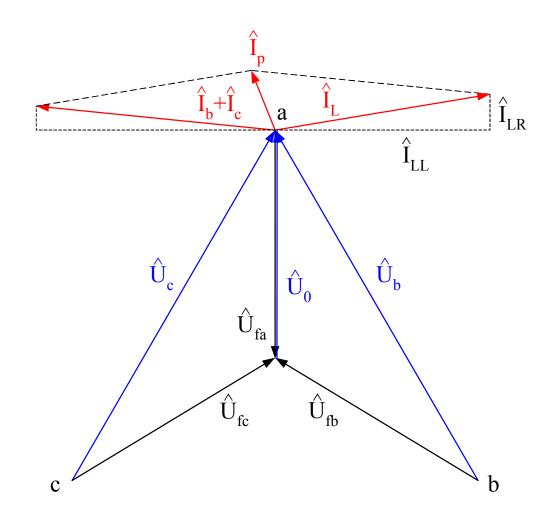
Coil power (reactive inductive)

$$\hat{S} = \hat{U}_0 \hat{I}_L^* = 3j\omega k_0 \hat{U}_0 \hat{U}_0^* = j\omega k_0 U^2 = Q_L$$

Ideal compensation: $I_p = 0$ in the fault point Real situation: residual current (small active)

- inaccurate inductance setting (error or intention)
- uncompensatable active component (power line conductance, coil R)
- higher harmonics

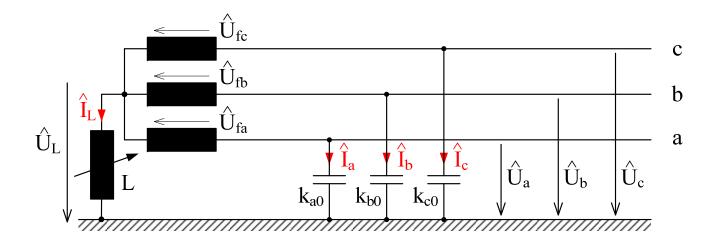
$$\hat{\mathbf{I}}_{p} = \left[\frac{1}{\mathbf{R}_{L}} + 3\mathbf{G}_{0} + j\left(3\omega\mathbf{k}_{0} - \frac{1}{\omega L}\right)\right]\hat{\mathbf{U}}_{0}$$



Arc-suppression coil tuning

L dimensioning by calculation, setting in the faultless state (for given system configuration).

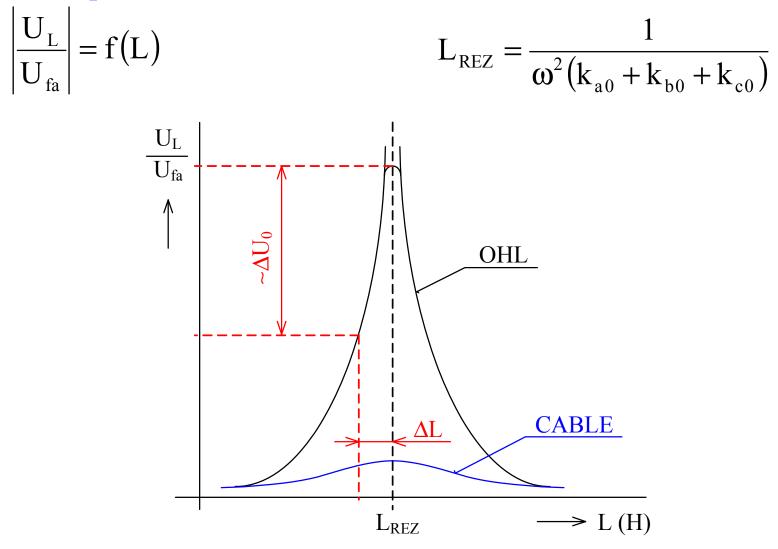
Tuning is done by magnetic circuit change by means of motor (air gap).



Coil voltage

$$\hat{U}_{L} = \frac{-\omega^{2}L(k_{a0} + \hat{a}^{2}k_{b0} + \hat{a}k_{c0})}{\omega^{2}L(k_{a0} + k_{b0} + k_{c0}) - 1}\hat{U}_{fa}$$

Resonance dependence



Overhead power lines

- higher capacitive unbalance
- maximum limited by resistances
- L_{REZ} compensates GF totally \rightarrow resonance coil
- setting by U_L measurement
- with small R the transformer neutral point is strained too much in resonance → intended (small) detuning → dissonance coil

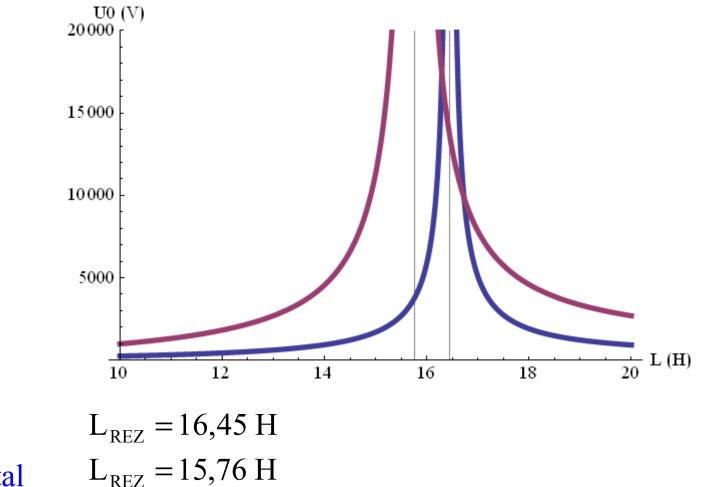
Cable power lines

• small capacitive unbalance \rightarrow flat curve \rightarrow difficult tuning



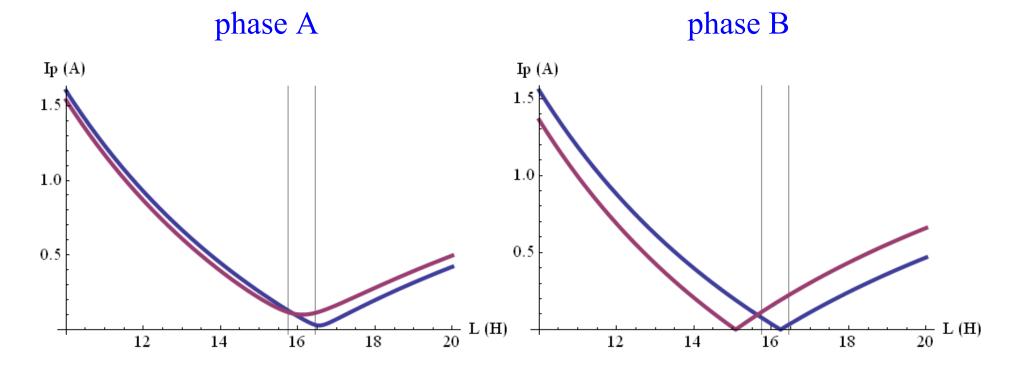


Neutral point voltage (talon blue, horizontal violet)

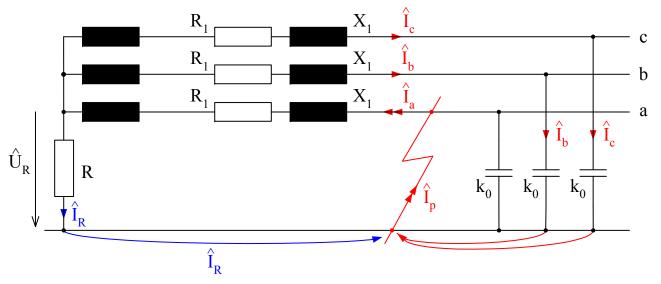


talon horizontal

Fault current for coil detuning (talon blue, horizontal violet)



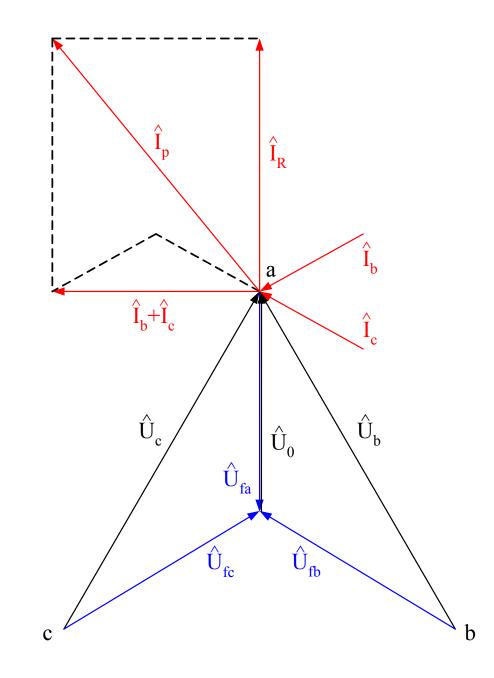
Cable systems grounded with the resistance



During the fault

- neutral point voltage almost phase-to-ground value
- I_p uncompensated
- I_p depends on the system extent x decreases with the distance from the transformer (short-circuit character)
- \bullet R value choice can influence I_p size and character

 $\hat{I}_{P} = -(1/R + j3\omega k_{0})U_{f}$



Neutral point voltage in a faultless state $(k_{b0} = (1 - \Delta)k_{c0}; k_{a0} = k_{c0} = 50 \cdot 4 \text{ nF} / \text{km} \cdot 50 \text{ km})$ $R_{uz} = 20 \Omega$

