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In[1]:= pom = pom;
Remove["Global`*"];
Off[FindMinimum::sszero];
$HistoryLength = 2;
SetDirectory[NotebookDirectory[]];
Off[NIntegrate::ncvb];

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In[7]:= Rs = 0.001;
Ls = 0.000001;
L = 0.000000173;
R1 = 0.000669;
R2 = 0.000669;
R3 = 0.000669;
Ampl = 500.;
ω = 314.;
T =  $\frac{2 * \text{Pi}}{\omega}$ ;
ut1 = Ampl * Sin[ω * t];
ut2 = Ampl * Sin[ω * t -  $\frac{2 \pi}{3}$ ];
ut3 = Ampl * Sin[ω * t +  $\frac{2 \pi}{3}$ ];
ut1,2 = ut1 - ut2;
ut1,3 = ut1 - ut3;
ut3,2 = ut3 - ut2;
Gmin = 0.00008;
Lg1 = 10 + 0 * Sin[0.1 * ω * t];
SeedRandom[1];
Lg2 = 10 + 0 * Sin[0.08 * ω * t + Random[]];
Lg3 = 10 + 0 * Sin[0.11 * ω * t + Random[]];
α = 0.05;
(*pripadne 0.0005*)
I0 = 10 (*A*);
φ0 = 0.0001;
φ1 = 0.0001;
P0 = 1000;
A = 40;
B = 10 (*V na cm*);
g0 = 100.; (*poc vodivosti*)

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In[35]:= ClearAll[derg];
derg[i_, g_, Lg_] := Module[{ena, den, nom},
  ena =  $E^{\left(\frac{-i^2}{i0^2}\right)}$ ;
  den =  $(-\phi0 - \phi1 * E^{(-\alpha * \text{Abs}[i])})$ ;
  nom =  $g - Gmin - \frac{i^2}{g * (A + B * Lg)^2} * (1 - ena) - \frac{i^2}{P0} * ena$ ;
   $\frac{\text{nom}}{\text{den}}$ 
];

```

```
In[37]:= matMrel =  $\begin{pmatrix} 1 & 0.5 & 0.4 \\ 0.5 & 1 & 0.5 \\ 0.4 & 0.5 & 1 \end{pmatrix};$  (*Matrix of relative mutual inductances *)
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dersis = {i1'[t], i2'[t], i3'[t]};
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```
In[39]:= uf := Union[Flatten[#]] &;
rceg := {g#[t] * u#[t] == i#[t], g#[t] == derg[i#[t], g#[t], Lg#[t], g#[0] == g0] &;
rg = uf@(rceg /@ Range[3]);
rcePrivod := {uin#[t] - u#[t] == R# * i#[t] + L * (matMrel.dersis)[[#]], i#[0] == 0} &;
rp = uf@(rcePrivod /@ Range[3]);
rTrafo[{k1_, k2_}] :=
  {uin_{k1}[t] - uin_{k2}[t] == Ls * i_{k1,k2}'[t] + i_{k1,k2}[t] * Rs + ut_{k1,k2}, i_{k1,k2}[0] == 0};
rT = uf@(rTrafo /@ {{1, 2}, {1, 3}, {3, 2}});
r123 = {0 == i1[t] + i1,2[t] + i1,3[t], i2[t] == i3,2[t] + i1,2[t], i3[t] == -i3,2[t] + i1,3[t]};
rDohr = Union[rg, rp, rT, r123];
nezname = Union[Cases[rDohr, _[t], {0, ∞}] /. {a_'[t] => a, a_[t] => a}];
tmax = 5 T;
res = NDSolve[rDohr, nezname, {t, 0, tmax}, StartingStepSize -> 10-16, MaxSteps -> 106,
  SolveDelayed -> False, MaxStepSize -> 10-3 T, AccuracyGoal -> 6, PrecisionGoal -> 4][[1]];
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```
Plot[Evaluate[{i1,2[t], i1,3[t], i3,2[t]} /. res],
  {t, tmax - T, tmax}, PlotRange -> All, AxesLabel -> {"t [s]", "i123 [A]"}]
```

