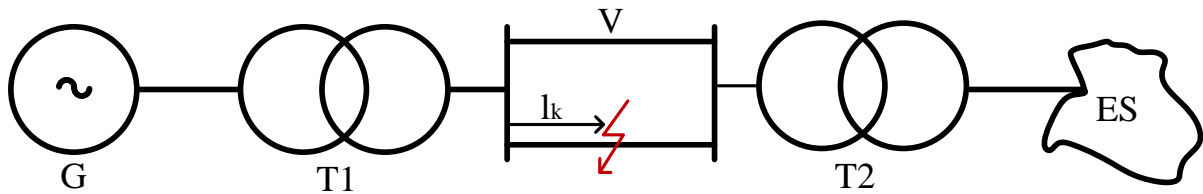


Calculate dynamic stability after three-phase short circuit on the line:



Parameters:

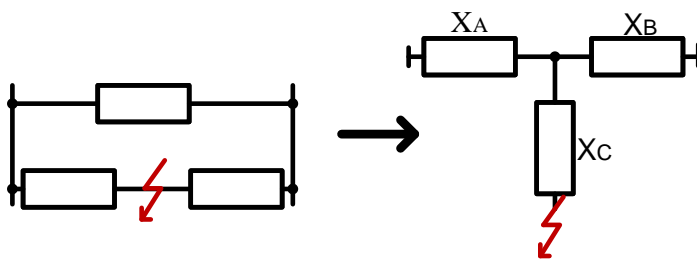
- G: $S_{nG} = 125 \text{ MVA}$, $x_{d'} = 25\%$, $T_g = 15 \text{ s}$
 T1: $S_{nT1} = 125 \text{ MVA}$, $u_k = 12\%$, $10,5/220 \text{ kV}$
 V: $x_{1\text{ved}} = 0,42 \Omega/\text{km}$, $l = 200 \text{ km}$, $l_k = 100 \text{ km}$
 T2: $S_{nT1} = 125 \text{ MVA}$, $u_k = 13\%$, $220/400 \text{ kV}$
 ES: $P = 100 \text{ MW}$, $\cos\varphi = 1$
-

Reference values:

- reference power $S_v = 100 \text{ MVA}$
- reference voltage $U_v = 220 \text{ kV}$

- 1- Before short circuit
- 2- During short circuit
- 3- After short circuit

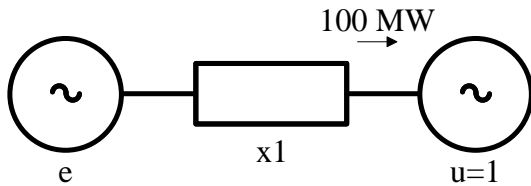
Δ -Y transformation:



$$x_{VAZ} = \frac{x_A \cdot x_B}{x_C}$$

- $x_1 = 0,487$
 $x_2 = 2,793$
 $x_3 = 0,574$

Before short circuit:



$$\delta_0 = 25,96^\circ$$

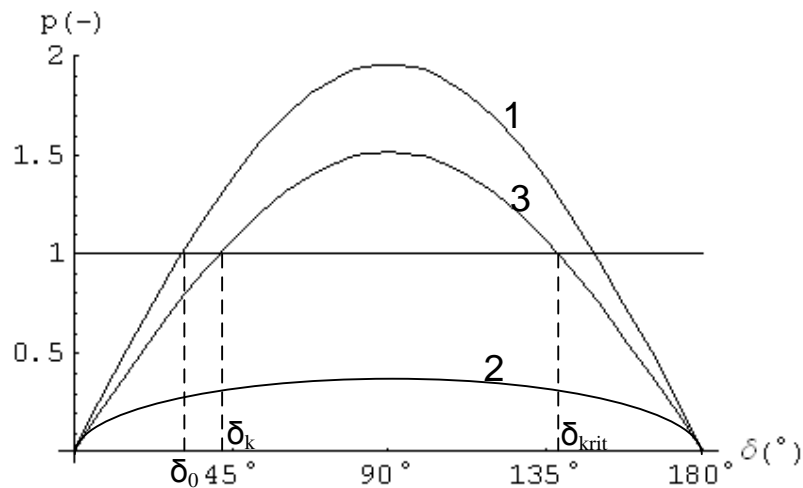
$$e = 1,11$$

$$p_{1max} = \frac{e \cdot u}{x_1} = 2,285$$

$$p_{2max} = 0,398$$

$$p_{3max} = 1,939$$

$$p_{mech} = 1$$



$$\delta_0 = 25,96^\circ$$

$$\delta_k = 31,04^\circ$$

$$\delta_{krit} = 148,96^\circ$$

Motion equation:

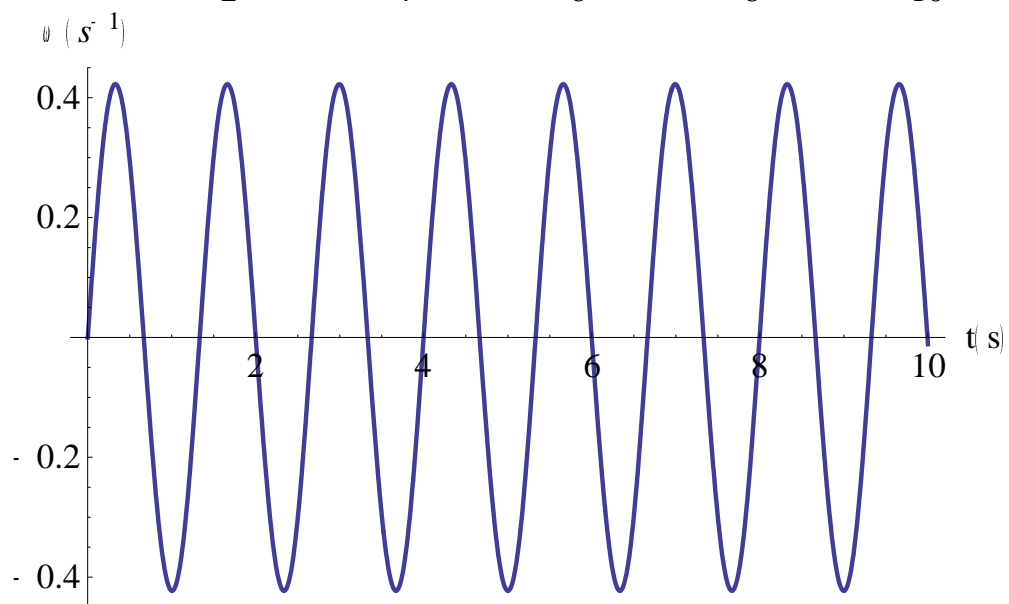
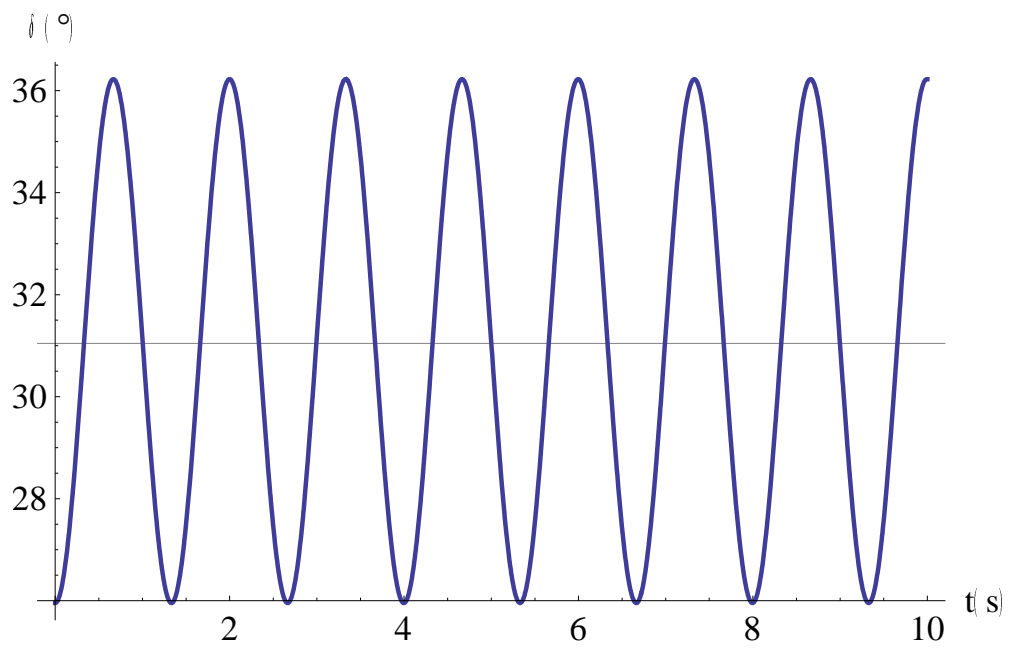
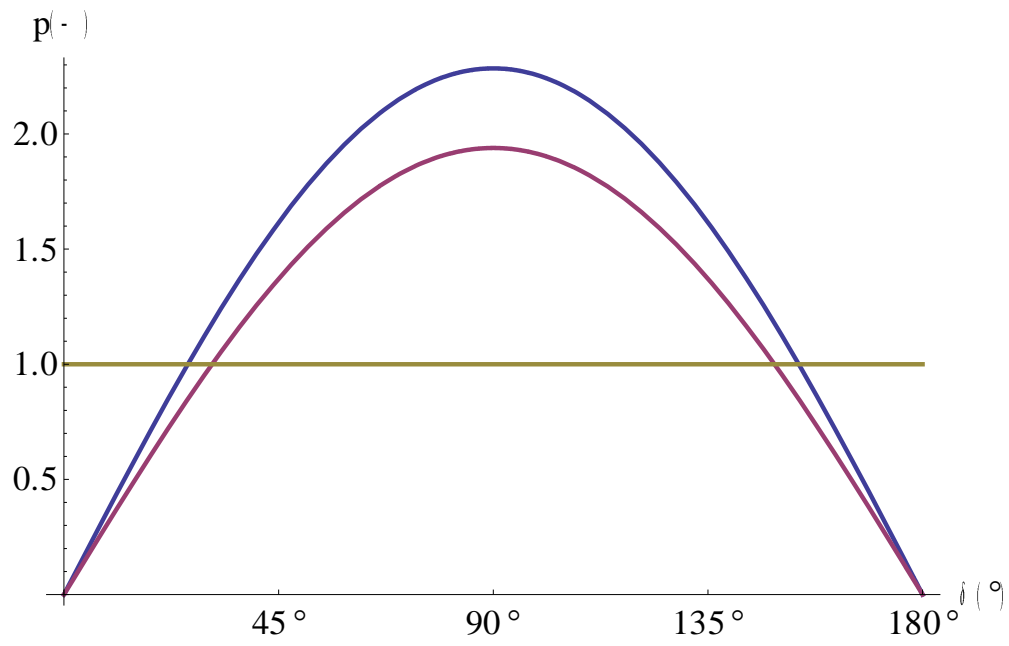
$$P_m - P_{max} * \sin(\delta(t)) = J * \omega(t) * \omega(t)' + B * \omega(t) * \delta(t)'$$

$$\omega(t) = \delta(t)' + \omega(0)$$

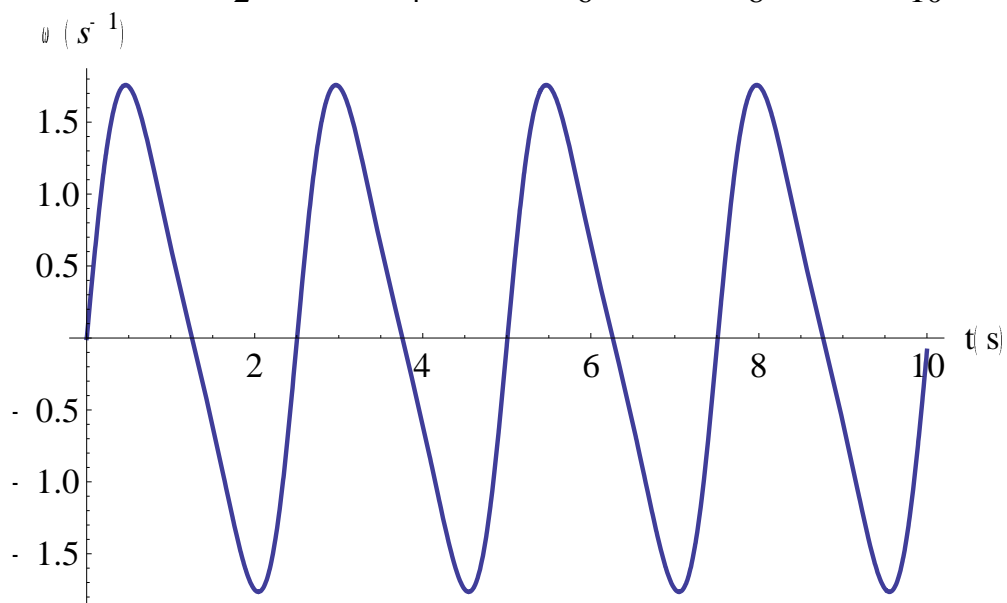
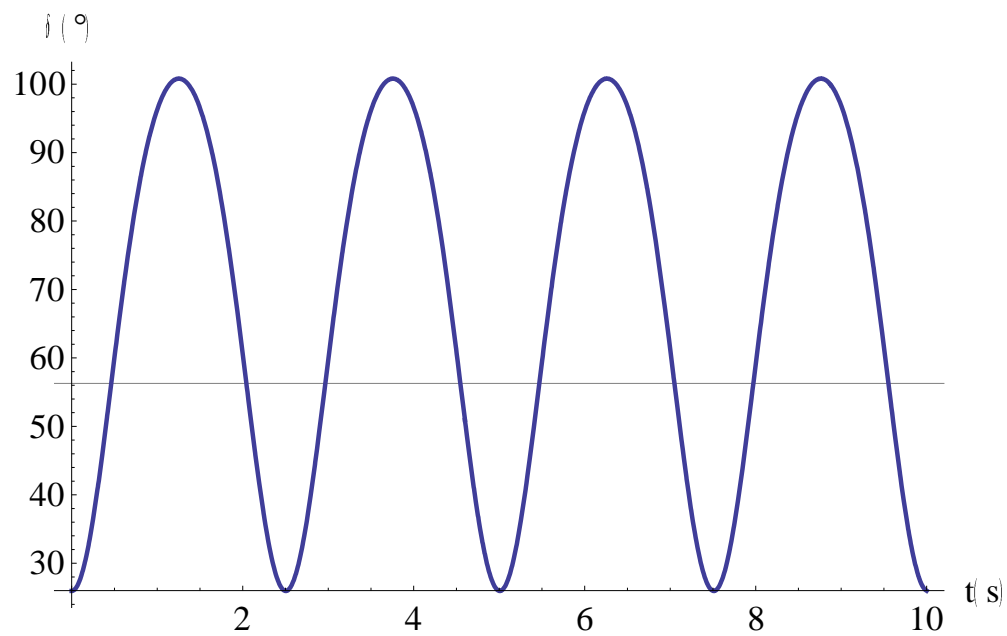
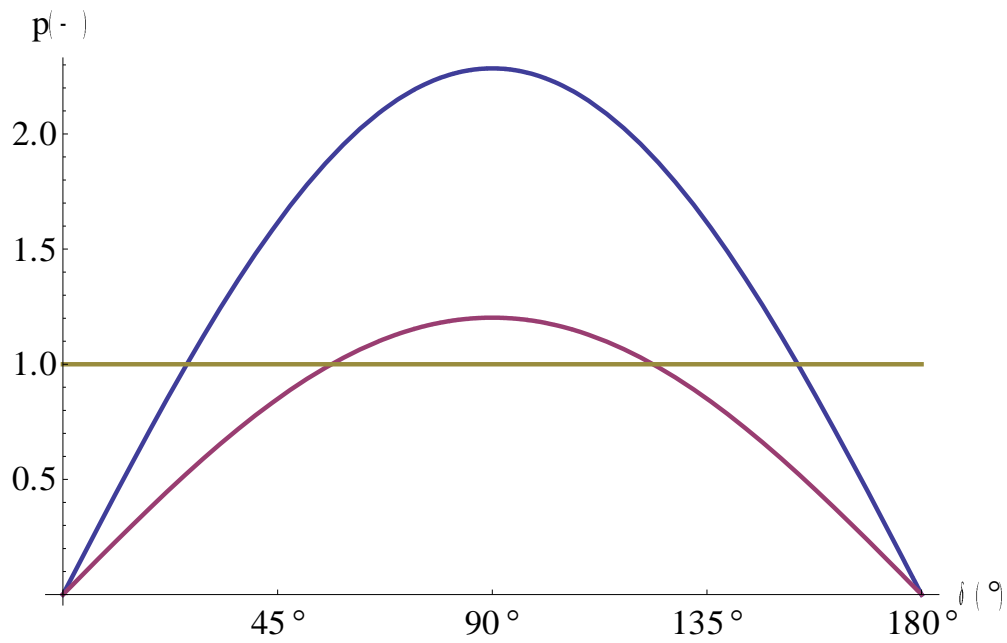
$$\delta(0) = \delta_0$$

$$\omega(0) = \omega_0$$

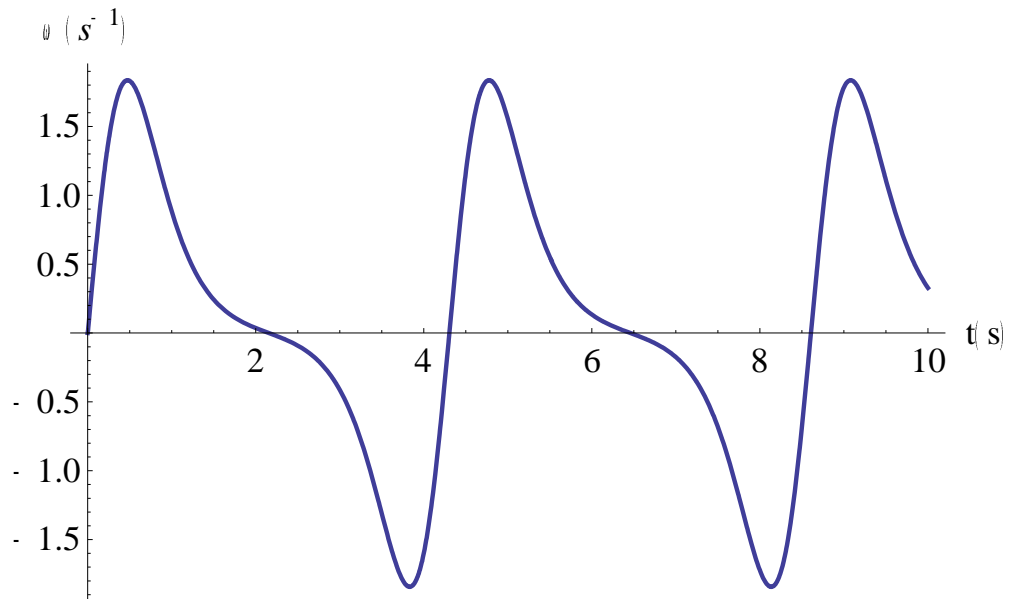
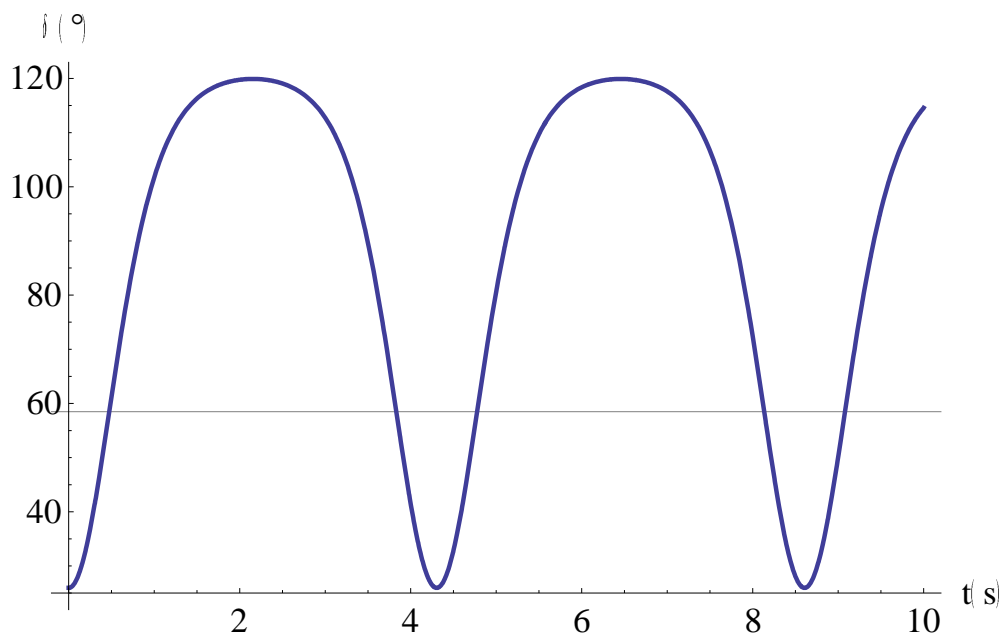
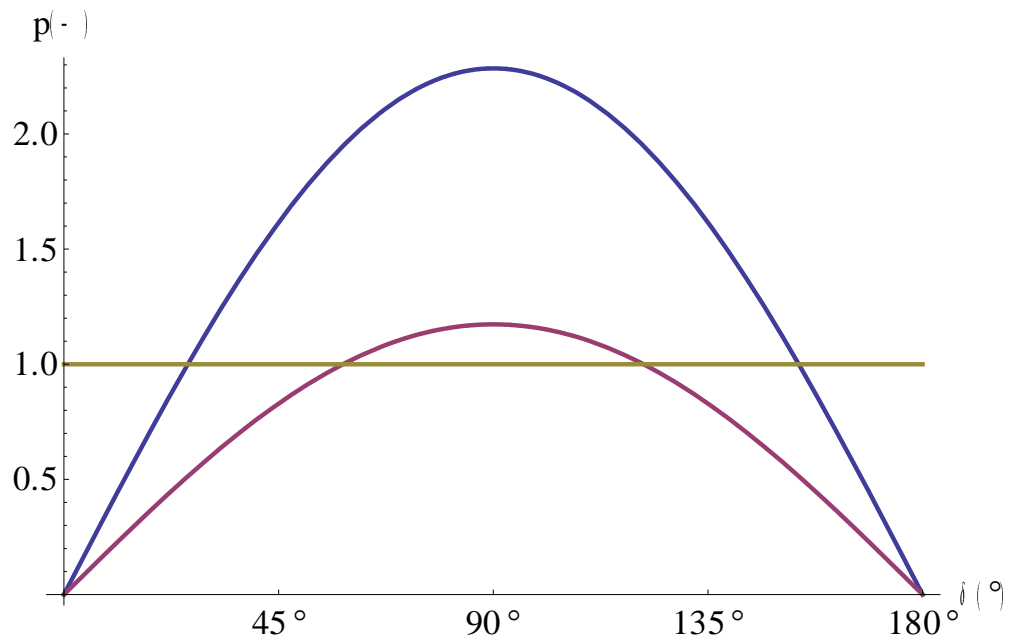
$$P_{\text{mech}} = 1; \quad P_{\text{max1}} = 2,285; \quad P_{\text{max2}} = 1,939$$



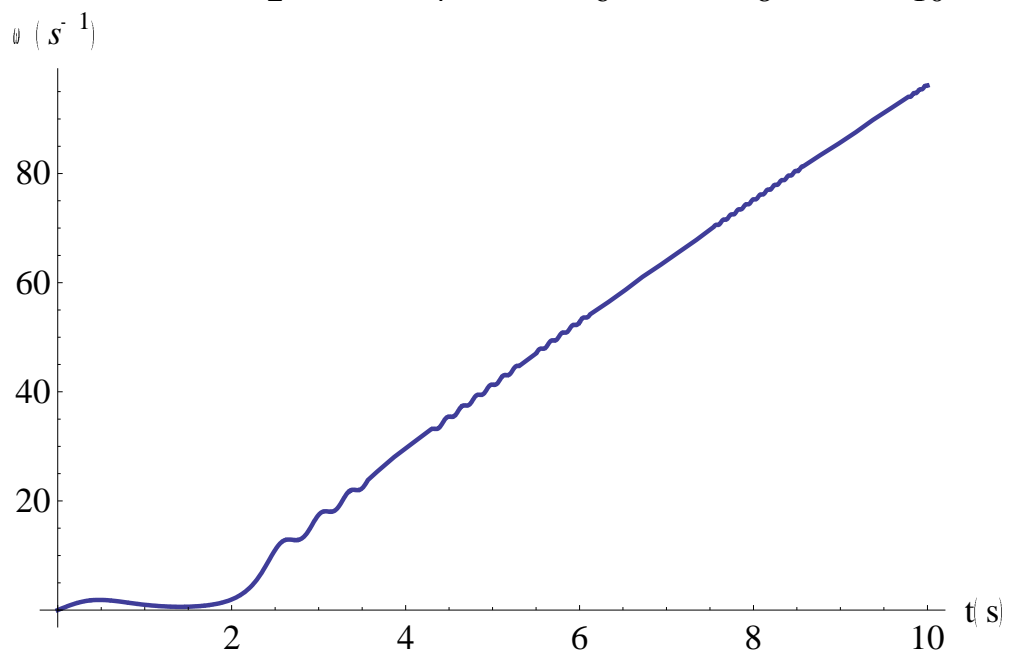
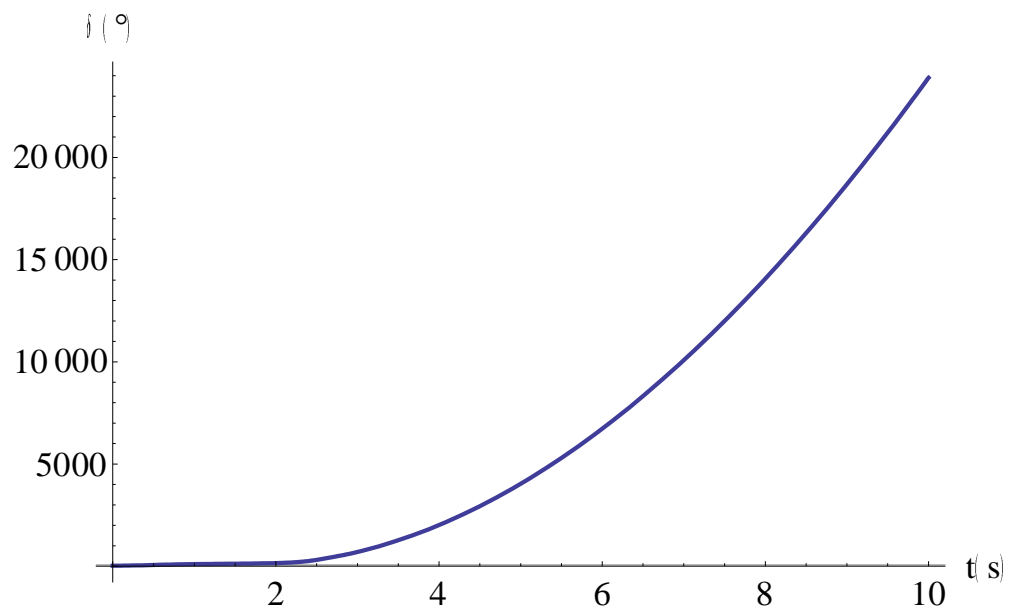
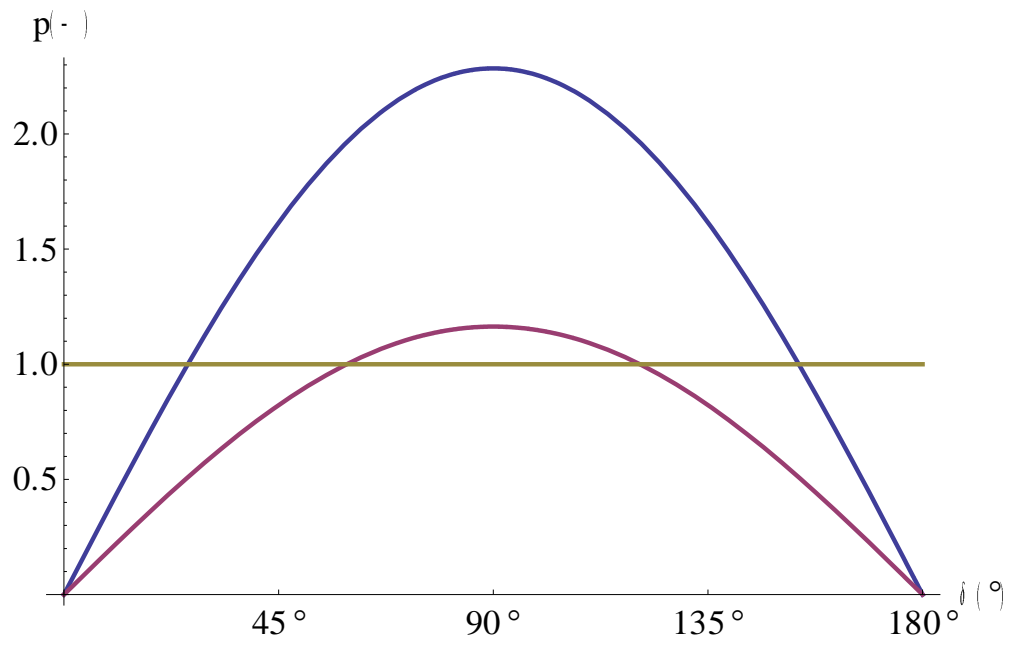
$$P_{\text{mech}} = 1; \quad P_{\text{max1}} = 2,285; \quad P_{\text{max2}} = 0,62 \cdot 1,939 = 1,202$$



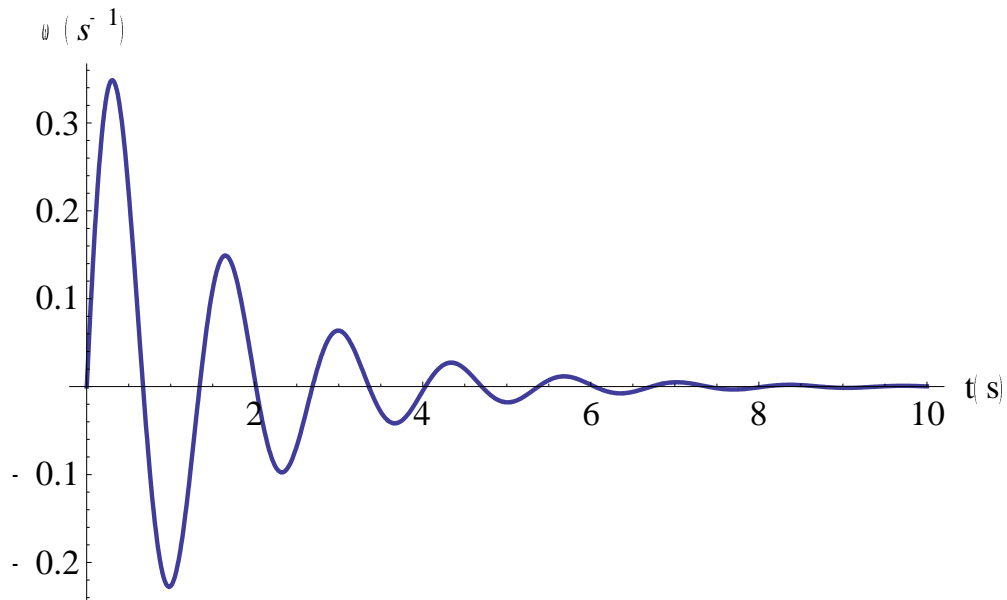
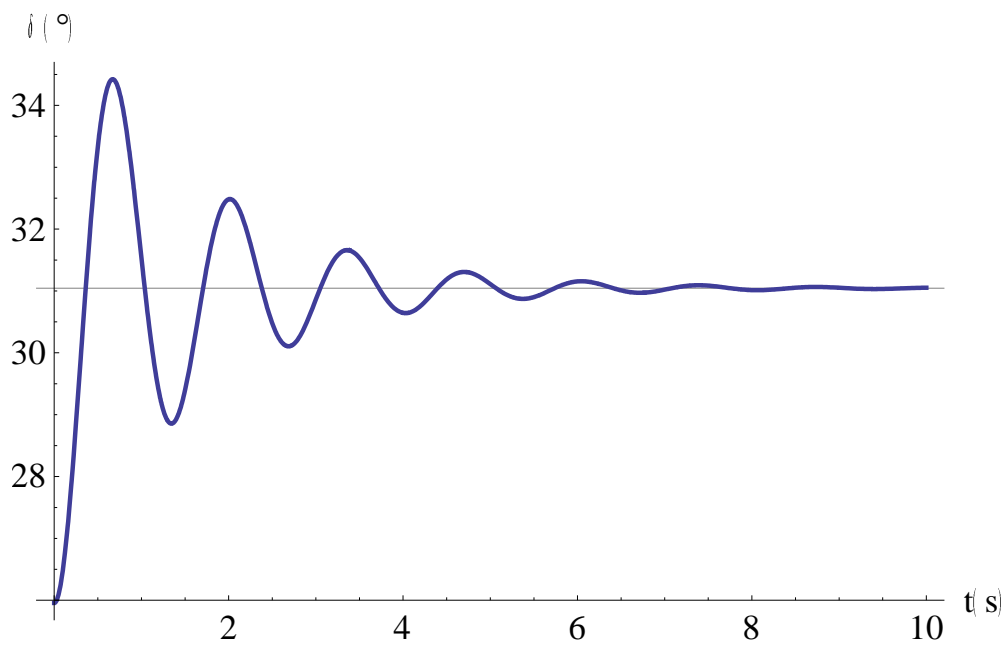
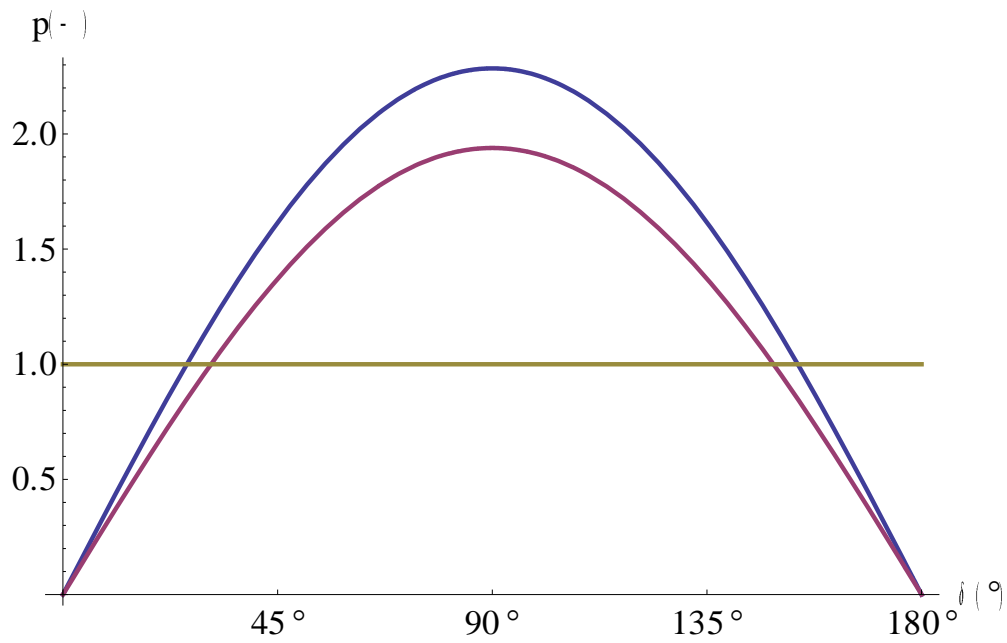
$$P_{\text{mech}} = 1; \quad P_{\text{max1}} = 2,285; \quad P_{\text{max2}} = 0,605 \cdot 1,939 = 1,173$$



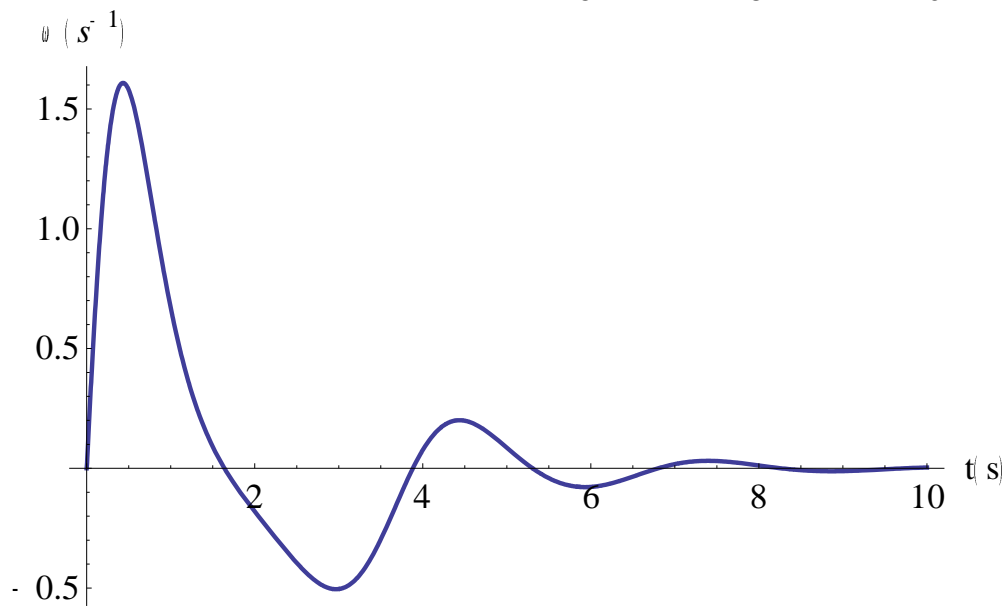
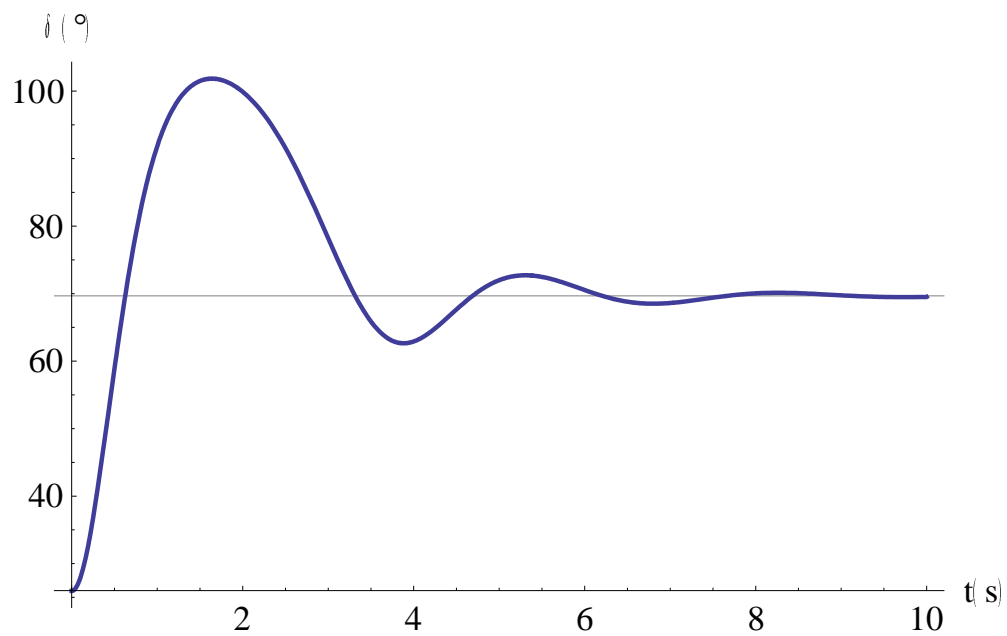
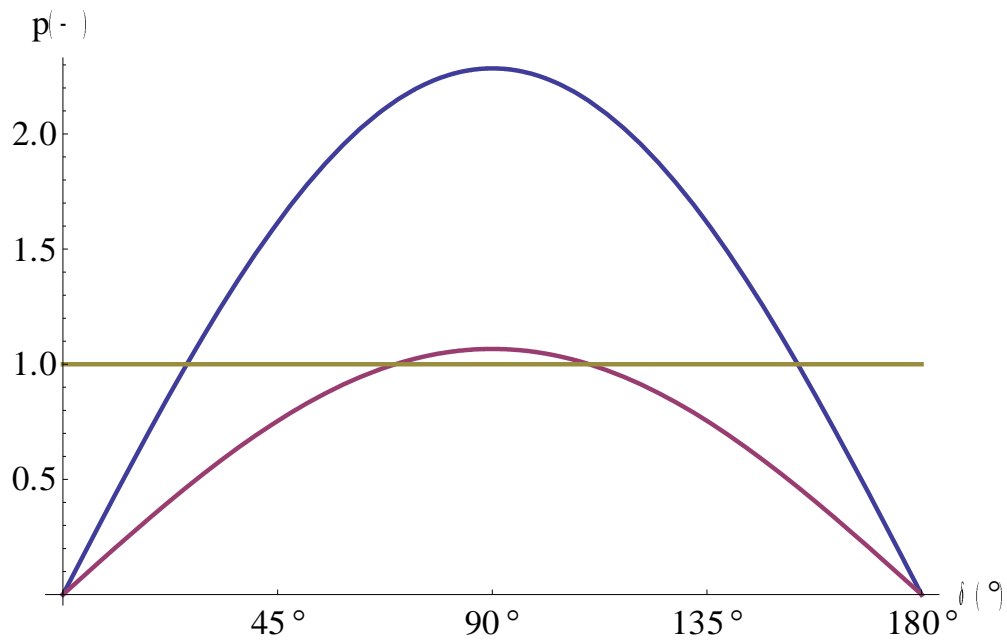
$$P_{\text{mech}} = 1; \quad P_{\text{max1}} = 2,285; \quad P_{\text{max2}} = 0,6 \cdot 1,939 = 1,163$$



$P_{mech} = 1$; $P_{max1} = 2,285$; $P_{max2} = 1,939$; *damping* $B = 0,0003$

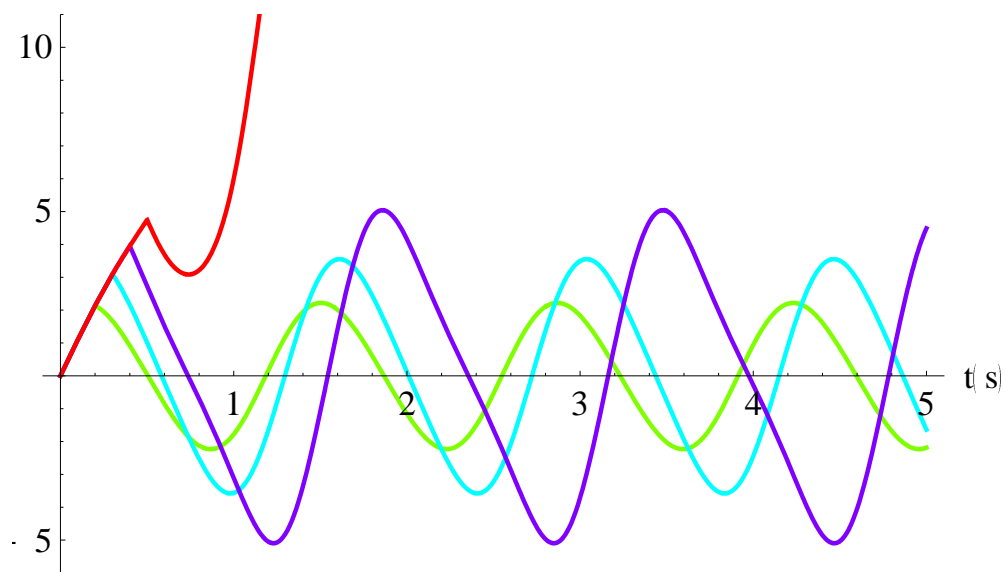
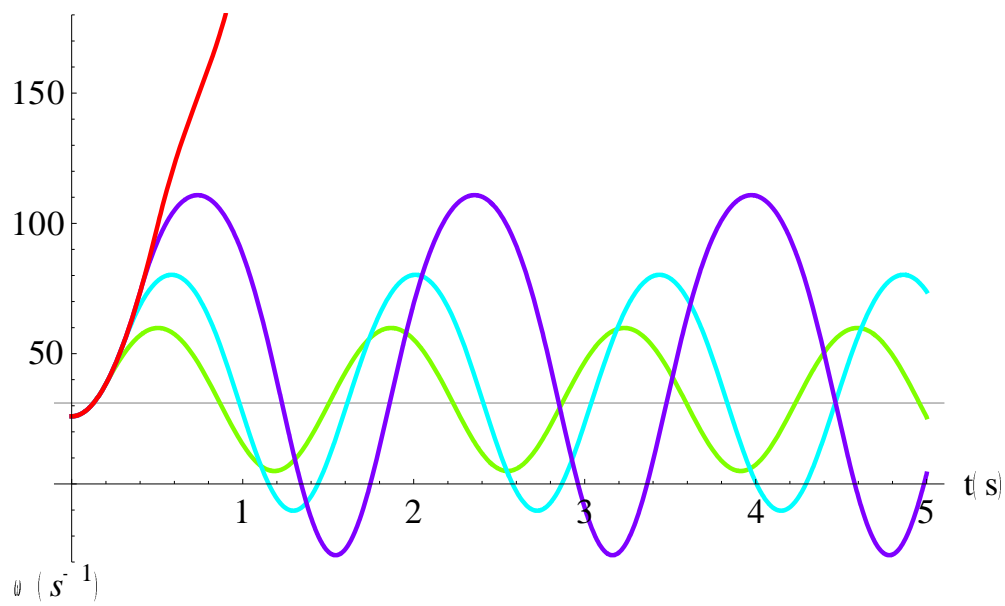
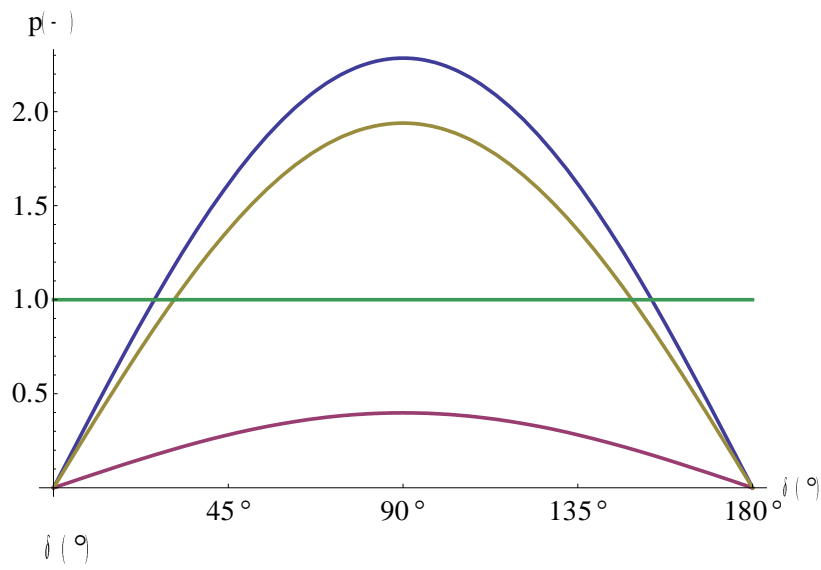


$P_{mech} = 1$; $P_{max1} = 2,285$; $P_{max2} = 0,55 \cdot 1,939 = 1,067$; damping $B = 0,0003$



$P_{\text{mech}} = 1; P_{\text{max1}} = 2,285; P_{\text{max2}} = 1,939; P_{\text{max3}} = 0,398$

Short circuit turn off: $t_{\text{vyp}} = 0,5\text{s } 0,4\text{s } 0,3\text{s } 0,2\text{s}$



$P_{mech} = 1$; $P_{max1} = 2,285$; $P_{max2} = 1,939$; $P_{max3} = 0,398$; *damping* $B = 0,0003$

Short circuit turn off: $t_{vyp} = 0,5s \ 0,4s \ 0,3s \ 0,2s$

