



linearita ruči salajici
ploše, je-li
dot mala

$$d^2 Q = \pi \epsilon_0 \gamma \cdot \cos \alpha_1 dS d\Omega$$

co sala' holmo

linearita ruči
malim prostornim uhlu
v danem smeru

Lambertovskí zákon

do celého uhlu :

γ

$$dQ = \int \pi \epsilon_0 \gamma \cos \alpha \cdot dS d\Omega =$$

$$= \int_{\varphi=0}^{2\pi} \int_{\vartheta=0}^{\pi/2} \cos \vartheta \sin \vartheta d\varphi d\vartheta \cdot \pi \epsilon_0 \gamma =$$

$\varphi=0$ $\vartheta=0$

$$= \pi \cdot dS \cdot \pi \epsilon_0 \gamma \Rightarrow \int \pi \epsilon_0 \gamma = \frac{1}{\pi} \frac{dQ}{dS} = \frac{\pi \epsilon_0 \gamma}{\pi}$$

$$dQ_{dS_1 \rightarrow dS_2} = \frac{1}{\pi} \pi \epsilon_0 \cdot \cos \alpha_1 \cdot dS_1 \cdot \frac{\cos \alpha_2 dS_2}{r^2}$$

$$dQ_{dS_1 \rightarrow \widehat{ve}} = \pi \epsilon_0 \cdot dS$$

$$\varphi_{dS_1 \rightarrow dS_2} = \frac{dQ_{dS_1 \rightarrow dS_2}}{dQ_{dS_1 \rightarrow \widehat{ve}}} = \frac{1}{\pi} \frac{\cos \alpha_1 \cos \alpha_2}{r^2} dS_2$$

$$\varphi_{dS_1 \rightarrow S_2} = \frac{1}{\pi} \int_{S_2} \frac{\cos \alpha_1 \cos \alpha_2}{r^2} dS_2$$

$$\varphi_{S_1 \rightarrow S_2} = \frac{1}{S_1} \int_{S_1} \varphi_{dS_1 \rightarrow S_2} dS_1 = \frac{1}{S_1 \pi} \int_{S_1} \int_{S_2} \frac{\cos \alpha_1 \cos \alpha_2}{r^2} dS_1 dS_2$$

$$1 \rightarrow 2, 2 \rightarrow 1 \Rightarrow$$

$$S_1 \varphi_{S_1 \rightarrow S_2} = S_2 \varphi_{S_2 \rightarrow S_1}$$

$$\begin{bmatrix} 1 - \varphi_{11} \rho_1 & -\rho_1 \varphi_{12} \\ -\rho_2 \varphi_{21} & 1 - \rho_2 \varphi_{22} \end{bmatrix} \begin{bmatrix} \psi_1 \\ \psi_2 \end{bmatrix} = \begin{bmatrix} \varepsilon_1 \pi_{e01} \\ \varepsilon_2 \pi_{e02} \end{bmatrix} \quad \text{--- 3}$$

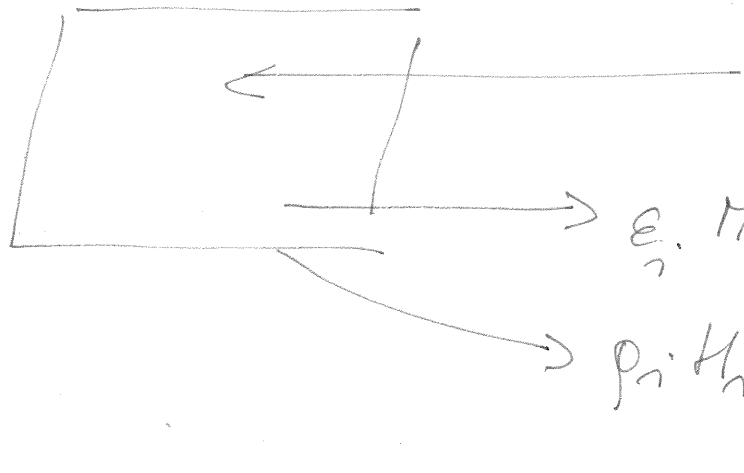
$$\begin{bmatrix} 1 - \varepsilon_1 & - (1 - \varepsilon_1) \\ - (1 - \varepsilon_2) \frac{s_1}{s_2} & 1 - (1 - \varepsilon_2) \left(1 - \frac{s_1}{s_2} \right) \end{bmatrix} \begin{bmatrix} \psi_1 \\ \psi_2 \end{bmatrix} = \begin{bmatrix} \varepsilon_1 \pi_{e01} \\ \varepsilon_2 \pi_{e02} \end{bmatrix}$$

Pobracovani' pohady o sala'ni

Zonalni' metoda

1) rozdelime zhoumanou oblast na zony, ve
ktorych mužeme považovat podstatné veličiny
za konstantní

2) zde systémy, kde je sala'ni dominantní


$$H_i = \sum_{j=1}^n w_j \varphi_{ji}$$
$$\left. \begin{array}{l} \rightarrow E_i \cdot Meo_i \\ \rightarrow p_i \cdot H_i \end{array} \right\} w_i = E_i \cdot Meo_i + p_i \sum_{j=1}^n w_j \varphi_{ji}$$

budi'ci
"holky"

upravme:

~~$$w_i = p_i \sum_{j=1}^N w_j \varphi_{ji}$$~~

$$p_i = 1 - E_i$$

(nepřítelství holky)

Pro celkový výhled můžeme i-tou plochu ale platí:

$$H_i S_i = \sum_{j=1}^N w_j S_j \varphi_{ji} \quad | : S_i$$

$$H_i = \sum_{j=1}^N w_j \underbrace{\frac{S_j}{S_i} \varphi_{ji}}_{\varphi_{ij}} = \sum_{j=1}^N w_j \varphi_{ij}$$

$$u_i - \rho_i \sum_{j=1}^N u_j \varphi_{ij} = \varepsilon_i \pi_{eoi}$$

$$\begin{bmatrix} 1 - \rho_1 \varphi_{11} & -\rho_1 \varphi_{12} & -\rho_1 \varphi_{13} & \dots \\ -\rho_2 \varphi_{21} & 1 - \rho_2 \varphi_{22} & -\rho_2 \varphi_{23} & \dots \\ \vdots & \vdots & \vdots & \ddots \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ u_n \end{bmatrix} = \begin{bmatrix} \varepsilon_1 \pi_{eoi} \\ \varepsilon_2 \pi_{eoi} \\ \vdots \\ \varepsilon_n \pi_{eoi} \end{bmatrix}$$

$$Z_{y'x} = u_i - H_i = \varepsilon_i \pi_{eoi} + \rho_i \cdot H_i - H_i =$$

$$= u_i - \frac{u_i - \varepsilon_i \pi_{eo}}{\rho_i} = \frac{u_i \rho_i - u_i + \varepsilon_i \pi_{eo}}{\rho_i} =$$

$$= \frac{-u_i (1 - \rho_i) + \varepsilon_i \pi_{eo}}{\rho_i} = \frac{\pi_{eo} \varepsilon_i - u_i \varepsilon_i}{\rho_i} =$$

$$= \frac{\varepsilon_i}{\rho_i} (\pi_{eo} - u_i)$$

(Pr) 1 těleso je nomtri drabito:

$$\varphi_{12} = 1$$

a vesala' na tche: $\varphi_{11} = 0$

podle definice: $S_2 \varphi_{21} = S_1 \varphi_{12} = S_1$

$$\Rightarrow \varphi_{21} = \frac{S_1}{S_2}$$

$$\varphi_{22} = 1 - \frac{S_1}{S_2}$$

$$H_i S_i = \sum_j w_j S_j \varphi_{ji}$$

i-ta
plocha

$$S_i \cdot \varepsilon_i \cdot \pi_{eoi}$$

$$S_i \cdot p_i \cdot H_i$$

$$w_i \cdot S_i$$

$$H_i = \frac{w_i - \varepsilon_i \pi_{eoi}}{p_i}$$

$$H_i = \sum_j w_j \frac{S_j}{S_i} \varphi_{ji} = \sum_j w_j \varphi_{ij}$$

$$w_i - \varepsilon_i \pi_{eoi} = p_i \sum_j w_j \varphi_{ij} \quad \parallel$$

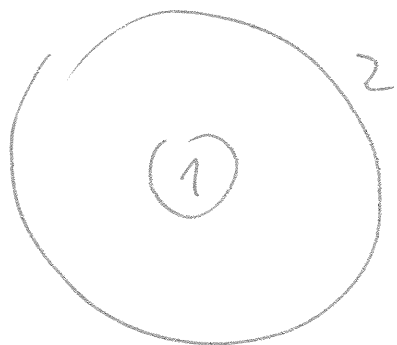
rovnice pro w_i , resp.

$$w_i - p_i \sum_j w_j \varphi_{ij} = \varepsilon_i \pi_{eoi}$$

$$Q_{y^{\text{tel}}} = W_i - H_i = W_i - \frac{W_i - \epsilon_i \cdot \pi_{\text{eo}i}}{\rho_i} =$$

$$= \frac{-W_i(1 - \rho_i) + \epsilon_i \cdot \pi_{\text{eo}i}}{\rho_i} = \frac{\epsilon_i}{\rho_i} (\pi_{\text{eo}} - W_i)$$

(Pr) 1 těleso novitě druheho :



$$\varphi_{12} = 1$$

$$\varphi_{11} = 0$$

$$S_2 \varphi_{21} = S_1 \varphi_{12} = S_1$$

$$\varphi_{21} = \frac{S_1}{S_2} \quad ; \quad \varphi_{22} = 1 - \frac{S_1}{S_2}$$

+ příložený příklad :

```
In[11]:= mat = {{1 - ϕ11 * ρ1, -ρ1 * ϕ12}, {-ρ2 * ϕ21, 1 - ρ2 * ϕ22}};
vect = {ε1 * M01, ε2 * M02};
res = Simplify[LinearSolve[mat, vect]]
```

$$\text{Out[13]} = \left\{ \frac{-M02 \epsilon2 \rho1 \phi12 + M01 \epsilon1 (-1 + \rho2 \phi22)}{-1 + \rho2 \phi22 + \rho1 (\phi11 + \rho2 \phi12 \phi21 - \rho2 \phi11 \phi22)}, \frac{M02 (\epsilon2 - \epsilon2 \rho1 \phi11) + M01 \epsilon1 \rho2 \phi21}{1 - \rho2 \phi22 - \rho1 (\phi11 + \rho2 \phi12 \phi21 - \rho2 \phi11 \phi22)} \right\}$$

```
In[24]:= dosad = {ρ1 → (1 - ε1), ρ2 → (1 - ε2), ϕ12 → 1, ϕ11 → 0, ϕ21 →  $\frac{S1}{S2}$ , ϕ22 →  $1 - \frac{S1}{S2}$ };
novres = Simplify[res /. dosad]
W1 = novres[[1]];
```

$$\text{Out[25]} = \left\{ \frac{M02 S2 (-1 + \epsilon1) \epsilon2 + M01 \epsilon1 (S1 (-1 + \epsilon2) - S2 \epsilon2)}{S1 \epsilon1 (-1 + \epsilon2) - S2 \epsilon2}, \frac{M01 S1 \epsilon1 (-1 + \epsilon2) - M02 S2 \epsilon2}{S1 \epsilon1 (-1 + \epsilon2) - S2 \epsilon2} \right\}$$

```
In[33]:= H1 = Simplify[ $\frac{W1 - \epsilon1 * M01}{\rho1}$  /. dosad]
qvysl = Simplify[W1 - H1]
```

$$\text{Out[33]} = \frac{M01 S1 \epsilon1 (-1 + \epsilon2) - M02 S2 \epsilon2}{S1 \epsilon1 (-1 + \epsilon2) - S2 \epsilon2}$$

$$\text{Out[34]} = \frac{(M01 - M02) S2 \epsilon1 \epsilon2}{S2 \epsilon2 + S1 (\epsilon1 - \epsilon1 \epsilon2)}$$


```
In[137]:= mat = {{1 - ϕ11 * ρ1, -ρ1 * ϕ12}, {-ρ2 * ϕ21, 1 - ρ2 * ϕ22}};
vect = {ε1 * M01, ε2 * M02};
res = Simplify[LinearSolve[mat, vect]]
```

General::spell1 : Possible spelling error: new symbol name "ϕ21" is similar to existing symbol "ϕ12".

General::spell1 : Possible spelling error: new symbol name "ε1" is similar to existing symbol "ρ1".

General::spell1 : Possible spelling error: new symbol name "ε2" is similar to existing symbol "ρ2".

$$\text{Out[139]} = \left\{ \frac{-M02 \epsilon2 \rho1 \phi12 + M01 \epsilon1 (-1 + \rho2 \phi22)}{-1 + \rho2 \phi22 + \rho1 (\phi11 + \rho2 \phi12 \phi21 - \rho2 \phi11 \phi22)}, \frac{M02 (\epsilon2 - \epsilon2 \rho1 \phi11) + M01 \epsilon1 \rho2 \phi21}{1 - \rho2 \phi22 - \rho1 (\phi11 + \rho2 \phi12 \phi21 - \rho2 \phi11 \phi22)} \right\}$$

```
In[140]:= dosad = {ρ1 → (1 - ε1), ρ2 → (1 - ε2), ϕ12 → 1, ϕ11 → 0, ϕ21 → S1/S2, ϕ22 → 1 - S1/S2};
novres = Simplify[res /. dosad]
W1 = novres[[1]];
```

$$\text{Out[141]} = \left\{ \frac{M02 S2 (-1 + \epsilon1) \epsilon2 + M01 \epsilon1 (S1 (-1 + \epsilon2) - S2 \epsilon2)}{S1 \epsilon1 (-1 + \epsilon2) - S2 \epsilon2}, \frac{M01 S1 \epsilon1 (-1 + \epsilon2) - M02 S2 \epsilon2}{S1 \epsilon1 (-1 + \epsilon2) - S2 \epsilon2} \right\}$$

```
In[143]:= H1 = Simplify[W1 - ε1 * M01 / ρ1 /. dosad]
qvysl = Simplify[W1 - H1]
```

$$\text{Out[143]} = \frac{M01 S1 \epsilon1 (-1 + \epsilon2) - M02 S2 \epsilon2}{S1 \epsilon1 (-1 + \epsilon2) - S2 \epsilon2}$$

$$\text{Out[144]} = \frac{(M01 - M02) S2 \epsilon1 \epsilon2}{S2 \epsilon2 + S1 (\epsilon1 - \epsilon1 \epsilon2)}$$

```
In[149]:= vyr = FullSimplify[qvysl /. {M01 → σ * T1^4, M02 → σ * T2^4}]
```

$$\text{Out[149]} = \frac{S2 (T1^4 - T2^4) \epsilon1 \epsilon2 \sigma}{S2 \epsilon2 + S1 (\epsilon1 - \epsilon1 \epsilon2)}$$

```
In[159]:= Numerator[vyr]
ε1 ε2 * S2
```

$$\text{Out[159]} = (T1^4 - T2^4) \sigma$$

```
In[158]:= Expand[Numerator[vyr] / Denominator[vyr]]
```

$$\text{Out[158]} = -\frac{S1}{S2} + \frac{1}{\epsilon1} + \frac{S1}{S2 \epsilon2}$$